# Supplementary Material for \Data-driven selection of the number of change-points via error rate control"

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This supplementary material contains the lemmas used in the proof of Theorem 1 (Appendix C), the proofs of Proposition 1, Theorems 1–3 and Corollaries 1–2 (Appendix D–F), and some additional simulation results (Appendix G).

# Appendix B: Equivalence of de nitions given by Eqs.(3) and (4)

- If there exists one  ${}_{k}^{*} \in \left[\frac{1}{2}(j_{-1}+j); \frac{1}{2}(j+j_{+1})\right]$  as (3), we have  ${}_{k}^{*}-j_{-1} \geq j-{}_{k}^{*}$  when  $j \geq {}_{k}^{*}$  or  $j_{+1}-{}_{k}^{*} > {}_{k}^{*}-j$  when  $j < {}_{k}^{*}$ , that is  $|j-{}_{k}^{*}| = \min_{j \in \mathcal{T}} |j-{}_{k}^{*}|$  from which j follows (4);
- On the contrary, if  $j = \arg\min_{j \in \mathcal{T}} |_{j} |_{k}^{*}|$  as the definition of (4), we have  $|_{k}^{*} \geq \frac{1}{2}(|_{j-1} + |_{j})$  due to  $|_{k}^{*} |_{j-1} > |_{k}^{*} |_{j}$  if  $|_{k}^{*} < |_{j}^{*}|$  Similarly,  $|_{k}^{*} < \frac{1}{2}(|_{j} + |_{j-1})$  holds for  $|_{k}^{*} > |_{j}$ . Say,  $|_{j}$  follows the definition of (3).

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## Appendix C: Auxiliary lemmas

**Lemma S.1** If the model (1) and Assumption 1 hold,  $n^{-1} = +O_p(K_n n^{-1=2})$ , where is some positive matrix depending on k's.

This lemma can be proved using the similar arguments in the Proposition 1 of Zou et al. (2020), thus the details are omitted here.

**Lemma S.2** [Bernstein's inequality] Let  $X_1; ...; X_n$  be independent centered random variables a.s. bounded by  $A < \infty$  in absolute value. Let  $^2 = n^{-1} \sum_{i=1}^n \mathbb{E}(X_i^2)$ . Then for all x > 0,

$$\Pr\left(\sum_{i=1}^{n} X_i \ge x\right) \le \exp\left(-\frac{x^2}{2n^{-2} + 2Ax = 3}\right)$$

The third one is a moderate deviation result for the mean; See Petrov (2002).

## Lemma S.3 (Moderate Deviation for the Independent Sum)

Suppose that  $X_1; \ldots; X_n$  are independent random variables with mean zero, satisfying  $\mathbb{E}(|X_j|^{2+q}) < \infty \ (j=1;2;\ldots)$  for some q>0. Let  $B_n=\sum_{i=1}^n \mathbb{E}(X_i^2)$ . Then

$$\frac{\Pr\left(\sum_{i=1}^{n} X_{i} > x\sqrt{B_{n}}\right)}{1 - \Phi(x)} \to 1 \quad \text{and} \quad \frac{\Pr\left(\sum_{i=1}^{n} X_{i} < -x\sqrt{B_{n}}\right)}{\Phi(-x)} \to 1;$$

as  $n \to \infty$  uniformly in x in the domain  $0 \le x$ .  $\{\log(1=L_n)\}^{1=2}$ , where  $L_n = B_n^{-1-\frac{q}{2}} \sum_{i=1}^n \mathbb{E}(|X_i|^{2+q})$ .

For notational convenience, we note that our estimation procedure can be reformulated as follows. Suppose we have two independent sets of d-dimensional observations  $\{S_1^O, \ldots, S_n^O\}$  and  $\{S_1^E, \ldots, S_n^E\}$  collected from the following multiple change-point model

$$S_{j}^{O} = \mu_{k}^{*} + U_{j}; S_{j}^{E} = \mu_{k}^{*} + V_{j}; j \in (\ _{k}^{*}; \ _{k+1}^{*}]; k = 0; \dots; K_{n};$$

where  $\mathsf{U}_1 \not: \ldots \not: \mathsf{U}_n \not: \mathsf{V}_1 \not: \ldots \not: \mathsf{V}_n$  are independent standardized noises satisfying  $\mathbb{E}(\mathsf{U}_1) = \mathsf{0}$  and  $\mathrm{Cov}(\mathsf{U}_1) = \mathrm{Cov}(\mathsf{V}_1) = \ _k^*$ . Let  $\underline{\mathcal{S}} = \min_{0 \le k \le \mathcal{K}_n} \mathrm{Eig}_{\min}(\ _k^*)$  and  $\mathcal{S} = \max_{0 \le k \le \mathcal{K}_n} \mathrm{Eig}_{\max}(\ _k^*)$ ,

where  $\operatorname{Eig_{min}}(\mathbf{A})$  and  $\operatorname{Eig_{max}}(\mathbf{A})$  denote the smallest and largest eigenvalues of a square matrix  $\mathbf{A}$ . By Assumption 1, we know that  $0 < \underline{\mathcal{S}} < \mathcal{S} < \infty$ . To keep the subscript consistent with the main body, we roughly let  $\mathsf{S}_{2i}^O$ ,  $\mathsf{U}_{2i}$ ,  $\mathsf{S}_{2i-1}^E$ ,  $\mathsf{V}_{2i-1}$  as 0 for  $i=1;\ldots;m$ .

The next one establishes an uniform bound for  $\|\sum_{i=k_1+1}^{k_2} \mathbf{U}_i\|$ .

**Lemma S.4** Suppose Assumption 1 holds. Then we have as  $n \to \infty$ ,

$$\Pr\left(\max_{(k_1;k_2)\in\mathcal{T}(I_n)}(k_2-k_1)^{-1}\left\|\sum_{i=k_1+1}^{k_2}\mathbf{U}_i\right\|^2>C\log n\right)=O(n^{1-\cdots});$$

for some large C>0 and any  $0<<-2^{-1}$ .

**Proof.** We shall show that the assertion holds when d=1 and the case for d>1 is straightforward by using the Bonferroni inequality. Denote  $M_n=n^{1=(--)}$  for some 0<<, and observe that

$$U_{i} = [U_{i}\mathbb{I}(|U_{i}| \leq M_{n}) - \mathbb{E}\{U_{i}\mathbb{I}(|U_{i}| \leq M_{n})\}] + [U_{i}\mathbb{I}(|U_{i}| > M_{n}) - \mathbb{E}\{U_{i}\mathbb{I}(|U_{i}| > M_{n})\}]$$
  
=:  $U_{i1} + U_{i2}$ :

It suffices to prove that the assertion holds with  $U_{i1}$  and  $U_{i2}$  respectively. Let  $x = \sqrt{C \log n}$  with a sufficiently large C,

$$\Pr\left(\max_{(k_{1}:k_{2})\in\mathcal{T}(!_{n})}(k_{2}-k_{1})^{-1}\left(\sum_{i=k_{1}+1}^{k_{2}}U_{i}\right)^{2}>X^{2}\right)$$

$$\leq \Pr\left(\max_{(k_{1}:k_{2})\in\mathcal{T}(!_{n})}(k_{2}-k_{1})^{-1}\left|\sum_{i=k_{1}+1}^{k_{2}}U_{i1}\right|>X=2\right)$$

$$+\Pr\left(\max_{(k_{1}:k_{2})\in\mathcal{T}(!_{n})}(k_{2}-k_{1})^{-1}\left|\sum_{i=k_{1}+1}^{k_{2}}U_{i2}\right|>X=2\right)$$

$$=:P_{1}+P_{2}:$$

On one hand, by the Bernstein inequality in Lemma S.2, we have

$$P_{1} \leq n^{2} \Pr \left( (k_{2} - k_{1})^{-1=2} \left| \sum_{i=k_{1}+1}^{k_{2}} U_{i1} \right| > x=2 \right) \leq 2n^{2} \exp \left\{ -\frac{W_{n} X^{2}}{C_{1} W_{n} + C_{2} M_{n} W_{n}^{1=2} X} \right\} = o(n^{1-\frac{1}{2}})$$

where  $C_1$ ;  $C_2$  are some positive constants and we use the assumption that  $< -2^{-1}$ .

On the other hand, according to Cauchy inequality and Markov inequality, we note that

$$\mathbb{E}^{2}\{|U_{i}|\mathbb{I}(|U_{i}|>M_{n})\}\leq \mathbb{E}(U_{i}^{2})\Pr(|U_{i}|>M_{n})\leq C_{3}n^{-}$$

for some constant  $C_3 > 0$ . Further, it yields  $\max_{(k_1:k_2) \in \mathcal{T}(!_n)} (k_2 - k_1)^{1-2} \mathbb{E}\{|U_i|\mathbb{I}(|U_i| > M_n)\} = o(1)$ : Thus, by Assumption 1 and Markov inequality, we have

$$P_{2} \leq \Pr\left(\max_{(k_{1}:k_{2})\in\mathcal{T}(!_{n})}(k_{2}-k_{1})^{-1=2}\sum_{i=k_{1}+1}^{k_{2}}|U_{i}|\mathbb{I}(|U_{i}|>M_{n})>x=4\right)$$

$$\leq \Pr\left(\max_{(k_{1}:k_{2})\in\mathcal{T}(!_{n})}(k_{2}-k_{1})^{-1=2}\sum_{i=k_{1}+1}^{k_{2}}|U_{i}|>x=2\mid\max_{i}|U_{i}|>M_{n}\right)\Pr\left(\max_{i}|U_{i}|>M_{n}\right)$$

$$\leq n\Pr\left(|U_{i}|>M_{n}\right)\leq C_{4}n^{1-\frac{1}{n}};$$

for some positive constant  $C_4$ . The lemma is proved.

A direct corollary of Lemma S.4 is the following lemma. Denote  $\mathsf{T}_{1j} = \sqrt{\frac{n_j\,n_{j+1}}{n_j+n_{j+1}}} \quad {}_{n}(\bar{\mathsf{S}}^{O}_{j} - \bar{\mathsf{S}}^{O}_{j+1})$  and  $\mathsf{T}_{2j} = \sqrt{\frac{n_j\,n_{j+1}}{n_j+n_{j+1}}} (\bar{\mathsf{S}}^{E}_{j} - \bar{\mathsf{S}}^{E}_{j+1})$ .

**Lemma S.5** Suppose Assumptions 1-2 hold. For those  $j \in \mathcal{I}_0$ , then we have as  $n \to \infty$ ,

$$\Pr\left\{\|\mathsf{T}_{kj}\|^2 > C(\log n + ! \frac{1}{n} \frac{2}{n})\right\} = O(n^{1-\frac{n}{2}}); \ k = 1/2$$

for some large C>0 and any  $0<<<-2^{-1}$ .

**Proof.** We take  $T_{2j}$  as example. By Assumption 2, if there exists a true change point k between  $\hat{j}_{-1}$  and  $\hat{j}_{+1}$ , it can only be either close to  $\hat{j}_{-1}$  or  $\hat{j}_{+1}$ , but not  $\hat{j}_{-1}$ . Without loss

of generality, assume  $0 \le {*\atop k} - {\hat{j}}_{-1} \le n$ . Then we note that

$$\begin{split} \|\mathbf{T}_{2j}\| &= \left\| \sqrt{\frac{n_{j}n_{j+1}}{n_{j} + n_{j+1}}} \left\{ \frac{1}{n_{j}} \sum_{i=\hat{j}-1+1}^{\hat{j}} \mathbf{V}_{i} - \frac{1}{n_{j+1}} \sum_{i=\hat{j}+1}^{\hat{j}+1} \mathbf{V}_{i} + \frac{\overset{*}{*} - \hat{j}-1}{n_{j}} (\boldsymbol{\mu}_{k}^{*} - \boldsymbol{\mu}_{k+1}^{*}) \right\} \right\| \\ &\leq \sqrt{\frac{n_{j}}{n_{j} + n_{j+1}}} \left\| n_{j}^{-1-2} \sum_{i=\hat{j}-1+1}^{\hat{j}} \mathbf{V}_{i} \right\| + \sqrt{\frac{n_{j+1}}{n_{j} + n_{j+1}}} \left\| n_{j+1}^{-1-2} \sum_{i=\hat{j}+1}^{\hat{j}+1} \mathbf{V}_{i} \right\| + \left\| \frac{\overset{*}{*} - \hat{j}-1}{n_{j}} (\boldsymbol{\mu}_{k}^{*} - \boldsymbol{\mu}_{k+1}^{*}) \right\| \\ &\leq \sqrt{\frac{n_{j}}{n_{j} + n_{j+1}}} \left\| n_{j}^{-1-2} \sum_{i=\hat{j}-1+1}^{\hat{j}} \mathbf{V}_{i} \right\| + \sqrt{\frac{n_{j+1}}{n_{j} + n_{j+1}}} \left\| n_{j+1}^{-1-2} \sum_{i=\hat{j}+1}^{\hat{j}+1} \mathbf{V}_{i} \right\| + t \cdot n^{-1-2} n \left\| \boldsymbol{\mu}_{k}^{*} - \boldsymbol{\mu}_{k+1}^{*} \right\| \\ &\leq 2 \max_{(k_{1}, k_{2}) \in \mathcal{T}(t, n)} (k_{2} - k_{1})^{-1-2} \left\| \sum_{i=k_{1}+1}^{k_{2}} \mathbf{V}_{i} \right\| + t \cdot n^{-1-2} n \left\| \boldsymbol{\mu}_{k}^{*} - \boldsymbol{\mu}_{k+1}^{*} \right\| : \end{split}$$

The assertion is immediately verified by using Lemma S.4.

## Appendix D: Proof of Proposition 1

The proof of this proposition follows similarly to Theorem 2 in Barber et al. (2020) which shows that the Model-X knockoff selection procedure incurs an inflation of the false discovery rate that is proportional to the errors in estimating the distribution of each feature conditional on the remaining features. Fix > 0 and for any threshold t > 0, define

$$R(t) = \frac{\sum_{j \in \mathcal{I}_0} \mathbb{I}(W_j \ge t; \Delta_j \le)}{1 + \sum_{j \in \mathcal{I}_0} \mathbb{I}(W_j \le -t)}:$$

Consider the event that  $\mathcal{A} = \{\Delta := \max_{j \in \mathcal{I}_0} \Delta_j \leq \}$ . Furthermore, for a threshold rule

It is crucial to get an upper bound for  $\mathbb{E}\{R(L) \mid \mathcal{Z}_O\}$ . In what follows, all the " $\mathbb{E}(\cdot)$ " denote the expectations given  $\mathcal{Z}_O$ . We have

$$\mathbb{E}\{R(L)\} = \sum_{j \in \mathcal{I}_{0}} \mathbb{E}\left\{\frac{\mathbb{I}(W_{j} \geq L; \Delta_{j} \leq )}{1 + \sum_{j \in \mathcal{I}_{0}} \mathbb{I}(W_{j} \leq -L)}\right\}$$

$$= \sum_{j \in \mathcal{I}_{0}} \mathbb{E}\left\{\frac{\mathbb{I}(W_{j} \geq L_{j}; \Delta_{j} \leq )}{1 + \sum_{k \in \mathcal{I}_{0}; k \neq j} \mathbb{I}(W_{k} \leq -L_{j})}\right\}$$

$$= \sum_{j \in \mathcal{I}_{0}} \mathbb{E}\left\{\frac{\mathbb{I}\left\{\frac{\mathbb{I}(W_{j} \geq L_{j}; \Delta_{j} \leq )}{1 + \sum_{k \in \mathcal{I}_{0}; k \neq j} \mathbb{I}(W_{k} \leq -L_{j})} \mid |W_{j}|; \mathbf{W}_{-j}\right\}\right\}$$

$$= \sum_{j \in \mathcal{I}_{0}} \mathbb{E}\left\{\frac{\Pr(W_{j} > 0 \mid |W_{j}|; W_{j-1}; W_{j+1}; \mathcal{Z}_{O}) \mathbb{I}(|W_{j}| \geq L_{j}; \Delta_{j} \leq )}{1 + \sum_{k \in \mathcal{I}_{0}; k \neq j} \mathbb{I}(W_{k} \leq -L_{j})}\right\}; \quad (S.1)$$

where the last step holds since the only unknown is the sign of  $W_j$  after conditioning on  $(|W_j|; W_{j-1}; W_{j+1})$ . By definition of  $\Delta_j$ , we have  $\Pr(W_j > 0 \mid |W_j|; W_{j-1}; W_{j+1}; \mathcal{Z}_O) \leq 1=2+\Delta_j$ .

Hence,

 $\mathbb{E}\{R(L)\}$ 

$$\leq \sum_{j \in \mathcal{I}_{0}} \mathbb{E} \left\{ \frac{\left(\frac{1}{2} + \Delta_{j}\right) \mathbb{I}\left(|W_{j}| \geq L_{j}; \Delta_{j} \leq\right)}{1 + \sum_{k \in \mathcal{I}_{0}; k \neq j} \mathbb{I}\left(W_{k} \leq -L_{j}\right)} \right\}$$

$$\leq \left(\frac{1}{2} + \right) \left[ \sum_{j \in \mathcal{I}_{0}} \mathbb{E} \left\{ \frac{\mathbb{I}\left(W_{j} \geq L_{j}; \Delta_{j} \leq\right)}{1 + \sum_{k \in \mathcal{I}_{0}; k \neq j} \mathbb{I}\left(W_{k} \leq -L_{j}\right)} \right\} + \sum_{j \in \mathcal{I}_{0}} \mathbb{E} \left\{ \frac{\mathbb{I}\left(W_{j} \leq -L_{j}\right)}{1 + \sum_{k \in \mathcal{I}_{0}; k \neq j} \mathbb{I}\left(W_{k} \leq -L_{j}\right)} \right\} \right]$$

$$= \left(\frac{1}{2} + \right) \left[ \mathbb{E} \left\{ R\left(L\right) \right\} + \sum_{j \in \mathcal{I}_{0}} \mathbb{E} \left\{ \frac{\mathbb{I}\left(W_{j} \leq -L_{j}\right)}{1 + \sum_{k \in \mathcal{I}_{0}; k \neq j} \mathbb{I}\left(W_{k} \leq -L_{j}\right)} \right\} \right] :$$

Finally, the sum in the last expression can be simplified as: if for all null j,  $W_j > -L_j$ , then the sum is equal to zero, while otherwise,

$$\sum_{j \in \mathcal{I}_0} \mathbb{E} \left\{ \frac{\mathbb{I} \left( W_j \le -L_j \right)}{1 + \sum_{k \in \mathcal{I}_0 : k \ne j} \mathbb{I} \left( W_k \le -L_j \right)} \right\} = \sum_{j \in \mathcal{I}_0} \mathbb{E} \left\{ \frac{\mathbb{I} \left( W_j \le -L_j \right)}{1 + \sum_{k \in \mathcal{I}_0 : k \ne j} \mathbb{I} \left( W_k \le -L_k \right)} \right\} = 1;$$

where the first step comes from the fact: for any j;k, if  $W_j \leq -\min(L_j;L_k)$  and  $W_k \leq -\min(L_j;L_k)$ , then  $L_j = L_k$ ; see Barber et al. (2020).

Accordingly, we have

$$\mathbb{E}\{R(L)\} \le \frac{1=2+1}{1=2-1} \le 1+5 :$$

Consequently, the assertion of this proposition holds.

# Appendix E: Proof of Lemmas A.1-A.2

Note that both the candidate change-points set  $\widehat{\mathcal{T}}_{p_n}$  and the statistics  $W_j$  are dependent with  $\mathcal{Z}_O$ . In fact, we derive the following two lemmas on the basis of conditional probability on  $\mathcal{Z}_O$ . To be specific, conditional on  $\mathcal{Z}_O$ ,  $\widehat{\mathcal{T}}_{p_n}$  is fixed as well as  $(\bar{\mathbf{S}}_j^O - \bar{\mathbf{S}}_{j+1}^O)^{\top}$   $_{n}$ . Due to the independence between  $\mathcal{Z}_E$  and  $\mathcal{Z}_O$ , the standard results for independent sum such as Lemmas S.2-S.3 can be applied for  $\bar{\mathbf{S}}_j^E - \bar{\mathbf{S}}_{j+1}^E$  in the following arguments.

#### Proof of Lemma A.1

Define  $_n = \{C(\log n + ! _n^{-1} _n^2)\}^{1=2}$  for a large C > 0 specified in Lemma S.5. Let  $\mathcal{A}_n = \{\mathbf{u} \in \mathbb{R}^d : \|\mathbf{u}\| \ge t_n\}$ . Then, we observe that

$$\frac{G(t)}{G_{-}(t)} - 1 = \frac{\sum_{j \in \mathcal{I}_{0}} \{ \Pr(\mathsf{T}_{1j}^{\top} \mathsf{T}_{2j} \ge t \mid \mathcal{Z}_{O}) - \Pr(\mathsf{T}_{1j}^{\top} \mathsf{T}_{2j} \le -t \mid \mathcal{Z}_{O}) \}}{\rho_{0} G_{-}(t)}$$

Conditional on  $\mathcal{Z}_O$ , we have two cases. Firstly, for the case  $\mathsf{T}_{1j} \in \mathcal{A}_n^c$ , by Lemma S.5 we obtain that

$$\frac{G(t)}{G_{-}(t)} - 1 \le \frac{\sum_{j \in \mathcal{I}_{0}} \Pr(\mathsf{T}_{1j}^{\top} \mathsf{T}_{2j} \ge t \mid \mathcal{Z}_{O})}{p_{0} G_{-}(t)} \le \frac{\sum_{j \in \mathcal{I}_{0}} \Pr(\|\mathsf{T}_{2j}\| > n \mid \mathcal{Z}_{O})}{p_{0} = p_{n}} = O_{p}(n^{1 - \frac{n}{2}} p_{n});$$

where the first inequality is due to  $t \leq G_{-}^{-1}(1=p_n)$ , and thus we claim that  $\frac{G(t)}{G(t)}-1=O_p(n^{1-\cdots}p_n)$ .

Next, we consider the case  $\mathsf{T}_{1j} \in \mathcal{A}_n$ . We introduce a new sequence of independent random variables  $\{\mathsf{B}_i\}$  defined as follows:

$$\mathsf{B}_{i} = \begin{cases} \frac{\sqrt{n_{j} \, n_{j+1}}}{n_{j} \sqrt{n_{j} + n_{j+1}}} \mathsf{V}_{i}; & \widehat{j}_{-1} < i \leq \widehat{j}; \\ -\frac{\sqrt{n_{j} \, n_{j+1}}}{n_{j+1} \sqrt{n_{j} + n_{j+1}}} \mathsf{V}_{i}; & \widehat{j}_{-1} < i \leq \widehat{j}_{+1}; \end{cases}$$

By Lemma S.3, we firstly verify that for any given  $\mathbf{u} \in \mathcal{A}_n$ ,

$$\frac{\Pr\left\{\sum_{i=\hat{j}_{-1}+1}^{\hat{j}+1}\mathbf{u}^{\top}\mathbf{B}_{i} \geq t \mid \mathcal{Z}_{O}\right\}}{1 - \Phi(t = \sqrt{}}$$

#### Proof of Lemma A.2

We only show the validity of the first formula and the second one hold similarly. Note that the G(t) is a deceasing and continuous function. Let  $z_0 < z_1 < \cdots < z_{d_n} \le 1$  and  $t_i = G^{-1}(z_i)$ , where  $z_0 = a_n = p_n$ ;  $z_i = a_n = p_n + a_n i = p_n$ ;  $d_n = [\{(p_n - a_n) = a_n\}^{1=}]$  with > 1. Note that  $G(t_i) = G(t_{i+1}) = 1 + o(1)$  uniformly in i. It is therefore enough to obtain the convergence rate of

$$D_n = \sup_{0 \le i \le d_n} \left| \frac{\sum_{j \in \mathcal{I}_0} \left\{ \mathbb{I}(W_j \ge t_i) - \Pr(W_j \ge t_i \mid \mathcal{Z}_O) \right\}}{\rho_0 G(t_i)} \right| :$$

Define  $S_j = \{k \in \mathcal{I}_0 : W_k \text{ is dependent with } W_j\}$  and further

$$D(t) = \mathbb{E}\left[\left\{\sum_{j\in\mathcal{I}_0} \mathbb{I}(W_j \geq t) - \Pr(W_j \geq t \mid \mathcal{Z}_O)\right\}^2 \mid \mathcal{Z}_O\right]:$$

It is noted that

$$D(t) = \sum_{j \in \mathcal{I}_0} \sum_{k \in \mathcal{S}_j} \mathbb{E} \left[ \left\{ \mathbb{I}(W_j \geq t) - \Pr(W_j \geq t \mid \mathcal{Z}_O) \right\} \left\{ \mathbb{I}(W_k \geq t) - \Pr(W_k \geq t \mid \mathcal{Z}_O) \right\} \mid \mathcal{Z}_O \right] \leq 2\rho_0 G(t)$$

Note that conditional on  $\mathcal{Z}_O$ ,  $W_1 ::::: W_{p_n}$  is a 1-dependent sequence and so is  $\mathbb{I}(W_j \geq t_i)$ . We can get

$$\Pr(D_{n} \geq ) \leq \sum_{i=0}^{d_{n}} \Pr\left(\left|\frac{\sum_{j \in \mathcal{I}_{0}} \{\mathbb{I}(W_{j} \geq t_{i}) - \Pr(W_{j} \geq t_{i} \mid \mathcal{Z}_{O})\}}{p_{0}G(t_{i})}\right| \geq \right) \\
\leq \frac{1}{2} \sum_{i=0}^{d_{n}} \frac{1}{p_{0}^{2}G^{2}(t_{i})} D(t_{i}) \leq \frac{2}{2} \sum_{i=0}^{d_{n}} \frac{1}{p_{0}G(t_{i})}.$$

Moreover, observe that

$$\sum_{i=0}^{d_n} \frac{1}{p_0 G(t_i)} = \frac{p_n}{p_0} \left( \frac{1}{a_n} + \sum_{i=1}^{d_n} \frac{1}{a_n + a_n i} \right)$$

$$\leq c \left( \frac{1}{a_n} + a_n^{-1} \sum_{i=1}^{d_n} \frac{1}{1+i} \right) \leq c a_n^{-1} \{ 1 + O(1) \} :$$

In sum, we can have  $\Pr(D_n \ge ) \to 0$  provided that  $a_n \to \infty$ .

# Appendix F: Proof of Theorems 1-3 and Corollaries 1-2

## Proof of Corollary 1

(i) By Assumption 2, we know that the event that  $|\mathcal{I}_1| = \mathcal{K}_n$  and for each  $\hat{j} \in \mathcal{I}_1$ ,  $|\hat{j} - \hat{j}| \le n$  occur with probability approaching one as  $n \to \infty$ . Therefore, in what follows we always implicitly work with the occurrence of this event. From the proof of Theorem 1, we know that L.  $\frac{2}{n}$ . Hence

$$\begin{split} &\Pr\left(W_{j} < L; \text{ for some } \widehat{j} \in \mathcal{I}_{1} \mid \mathcal{Z}_{O}\right) \\ &\leq \mathcal{K}_{n} \Pr\left(\frac{n_{j} n_{j+1}}{n_{j} + n_{j+1}} (\bar{\mathbf{S}}_{j}^{O} - \bar{\mathbf{S}}_{j+1}^{O})^{\top} \quad n(\bar{\mathbf{S}}_{j}^{E} - \bar{\mathbf{S}}_{j+1}^{E}) < L \mid \mathcal{Z}_{O}\right) \\ &\leq \mathcal{K}_{n} \Pr\left(\frac{n_{j} n_{j+1}}{n_{j} + n_{j+1}} (\bar{\mathbf{U}}_{j} - \bar{\mathbf{U}}_{j+1})^{\top} \quad n(\bar{\mathbf{V}}_{j} - \bar{\mathbf{V}}_{j+1}) + O_{\rho}^{+}(! n \min_{1 \leq k \leq K_{n}} \|\boldsymbol{\mu}_{k+1}^{*} - \boldsymbol{\mu}_{k}^{*}\|^{2}) < L \mid \mathcal{Z}_{O}\right) \\ &\leq \mathcal{K}_{n} \Pr\left(O_{\rho}^{+}(! n \min_{1 \leq k \leq K_{n}} \|\boldsymbol{\mu}_{k+1}^{*} - \boldsymbol{\mu}_{k}^{*}\|^{2}) \leq L\right) \\ &+ \mathcal{K}_{n} \Pr\left(\frac{n_{j} n_{j+1}}{n_{j} + n_{j+1}} (\bar{\mathbf{U}}_{j} - \bar{\mathbf{U}}_{j+1})^{\top} \quad n(\bar{\mathbf{V}}_{j} - \bar{\mathbf{V}}_{j+1}) > O_{\rho}^{+}(! n \min_{1 \leq k \leq K_{n}} \|\boldsymbol{\mu}_{k+1}^{*} - \boldsymbol{\mu}_{k}^{*}\|^{2}) \mid \mathcal{Z}_{O}\right) \rightarrow 0 \end{split}$$

in probability, where we use Lemma S.4. The result immediately holds.

(ii) From (i), we have  $\lim_{n\to\infty} \Pr(\mathcal{M} \supseteq \mathcal{I}_1) = 1$ . Here, we only need to prove  $\lim_{n\to\infty} \Pr(\mathcal{M} \subseteq \mathcal{I}_1) = 1$ , which is equivalent to show that  $\lim_{n\to\infty} \Pr(\mathcal{M} \cap \mathcal{I}_0 = \emptyset) = 1$ .

It is noted that

$$\Pr(W_j \geq L; \text{ for some } j \in \mathcal{I}_0 \mid \mathcal{Z}_O) \leq \sum_{j \in \mathcal{I}_0} \Pr(W_j \geq L \mid \mathcal{Z}_O) \sim p_0 \frac{n}{p_n}. \quad K_n : j \in \mathcal{I}_0$$

By using the condition  $K_n \to 0$ , the corollary is proved.

#### Proof of Theorem 1

Following the notations in Section 2, assume  $\hat{j} \in \mathcal{M}$  is an informative point and  $\hat{j}$  is its corresponding true change-point such that  $|\hat{j} - \hat{j}| \leq n$  by Assumption 2. Note that  $|\hat{k} \in \widetilde{\mathcal{M}}$  is the selected one such that  $|\hat{k} - \hat{j}| = \min_{j \in \widetilde{\mathcal{I}}_{p_n}} |\hat{k} - \hat{j}|$ . Because  $\widetilde{\mathcal{M}}$  and  $\widetilde{\mathcal{M}}$  have

the same cardinality, we only need to show that  $\tilde{k} \in \mathcal{I}_1(\tilde{\mathcal{T}}_{p_n})$ , say

$$|\tilde{k}_k - \tilde{k}_j| = \min_{\tilde{k}_j \in \tilde{\mathcal{T}}_{p_n}} |\tilde{k}_j - \tilde{k}_j|$$

 $(\mathbf{S}_{\mathbf{k}}) = \mathbf{f}_{\mathbf{n}} \mathbf{f}_{\mathbf{n}}$ 

(ii) Let  $a_n = (C \log n)^{1-2}$ , where C > 0 is specified in Lemma S.5. Define  $\mathcal{B}_n = \{\mathbf{u} \in \mathbb{R}^d : \|\mathbf{u}\| \geq t = a_n\}$ . Let  $C = \bigcap_{j \in \mathcal{I}_0} \{|\tilde{W}_j| \leq j\}$ , where j satisfies  $\Pr(|\tilde{W}_j| > j \mid \mathcal{Z}_O) = b_n$  and  $b_n$  be a sequence satisfies the conditions that  $b_n \to 0$ ,  $p_n b_n \to 0$  and  $n^{-2} b_n \to \infty$ . According to the condition  $p_n n^{--2} \to 0$  in the theorem, such  $b_n$  is well defined. By the definition of  $\tilde{W}_j$ , we know that  $\mathbb{E}(\tilde{W}_j) = 0$  for all  $\hat{j} \in \mathcal{I}_0$ . Moreover, by Lemma S.5, we have  $j \in \mathcal{A}_n^2$  uniformly in j.

According to Proposition 1, we have

$$\operatorname{Pr}\left(\max_{j\in\mathcal{I}_{0}}\Delta_{j} > \mid \mathcal{Z}_{O}\right) = \operatorname{Pr}\left(\max_{j\in\mathcal{I}_{0}}\Delta_{j} > \mid \mathcal{C};\mathcal{Z}_{O}\right)\operatorname{Pr}(\mathcal{C}\mid\mathcal{Z}_{O}) + \operatorname{Pr}\left(\max_{j\in\mathcal{I}_{0}}\Delta_{j} > \mid \mathcal{C}^{c}\mid\mathcal{Z}_{O}\right) \\
\leq \operatorname{Pr}\left(\max_{j\in\mathcal{I}_{0}}\Delta_{j} > \mid \mathcal{C};\mathcal{Z}_{O}\right) + \operatorname{Pr}(\mathcal{C}^{c}\mid\mathcal{Z}_{O}) := A_{1} + A_{2}:$$

By the definition of  $b_n$ ,  $A_2 = o_p(1)$ . It remains to handle  $A_1$ .

Notice that conditional on  $\mathcal{C}$ ,

$$\max_{j \in \mathcal{I}_0} \Delta_j \le \max_{j \in \mathcal{I}_0} \sup_{0 \le t \le j} |f_j(-t) = f_j(t) - 1|; \tag{S.3}$$

where  $f_j(\cdot)$  is the density of  $\tilde{W}_j$  conditional on  $\mathcal{Z}_O$ . It remains to prove that the right-hand side of (S.3) goes to zero as  $n \to \infty$ .

Denote  $\tilde{\mathsf{T}}_{1j} = \sqrt{\frac{n_j n_{j+1}}{n_j + n_{j+1}}} \quad n(\tilde{\mathsf{S}}_{Lj}^O - \tilde{\mathsf{S}}_{Rj}^O) = \mathsf{u}$  given  $\mathcal{Z}_O$ . In a similar way to the proof of Lemma A.1, we consider two cases for  $\mathsf{u}$ . As to the case  $\mathsf{u} \in \mathcal{B}_n^c$ ,  $\max_{j \in \mathcal{I}_0} \Delta_j = O_p\{(n^{-2}b_n)^{-1}\}$  by the definition of j and  $0 \le t \le j$ . On the other hand, we consider the case  $\mathsf{u} \in \mathcal{B}_n$ . Then, for  $j \in \mathcal{I}_0$  by Lemma S.3, we have

$$f_j(t) = \{\tilde{\Phi}(t=s) - \tilde{\Phi}(t=s-)\}\{1 + o_p(1)\} = \frac{1}{s} (t=s)\{1 + o_p(1)\};$$

where  $S = \sqrt{\mathbf{u}^{\top} \mathbf{u}}$ . Similarly, we also have  $f_j(-t) = \frac{1}{s} (-t=s)\{1 + o_p(1)\}$ , which yields that the right-hand side of (S.3) goes to zero since (-t=s) = (t=s) and (t=s) is bounded. Then, the result (ii) in the theorem holds.

# Appendix G: Additional simulation results

## Selection of $p_n$ and $l_n$

Table S1 reports the FDR, TPR and  $\widehat{K}$  of MOPS in conjunction with OP, PELT and WBS detection algorithms with different  $p_n$  and  $l_n$  under Example I. We consider the error from N(0;1) and fix n=4096,  $K_n=15$  and SNR=0.5. We observe that different values of  $c \in (1;2]$  for  $p_n = \lfloor cn^{2-5} \rfloor$  and  $\in [0:3;0:5]$  for  $l_n = n$  present similar results and their FDRs are not significantly different. Thus we recommend  $p_n = \lfloor 2n^{2-5} \rfloor$  and  $l_n = \min(\lfloor n^{0.5} \rfloor;60)$  in the simulation studies.

Table S1: FDR(%), TPR(%) and  $\widehat{K}$  of MOPS in conjunction with OP, PELT and WBS detection algorithms when error follows N(0;1), n=4096,  $K_n=15$  and SNR=0.5 under Example I. The  $p_n$  is chosen as  $p_n=\lfloor cn^{2+5}\rfloor$  with c=1:2;1:5;2 and  $l_n=n$  with =0:3;0:4;0:5.

		= 0:3				= 0:4		= 0.:5			
p <sub>n</sub>	Method	FDR	TPR	Ŕ	FDR	TPR	Ŕ		FDR	TPR	Ŕ
	M-OP	19 <i>:</i> 8	91 <i>:</i> 3	17 <i>:</i> 7	19 <i>:</i> 1	92 <i>:</i> 7	17 <i>:</i> 9		18 <i>:</i> 9	95 <i>:</i> 2	18 <i>:</i> 3
1 <i>:</i> 2 <i>n</i> <sup>2=5</sup>	M-PELT	19 <i>:</i> 5	91:2	17 <i>:</i> 5	19 <i>:</i> 4	93 <i>:</i> 1	18:0		19 <i>:</i> 9	95 <i>:</i> 7	18 <i>:</i> 8
	M-WBS	16 <i>:</i> 9	91 <i>:</i> 8	17 <i>:</i> 3	17 <i>:</i> 2	92 <i>:</i> 3	17 <i>:</i> 5		19 <i>:</i> 5	95 <i>:</i> 3	18 <i>:</i> 5
	M-OP	18 <i>:</i> 6	90:0	17 <i>:</i> 2	21 <i>:</i> 0	92 <i>:</i> 9	18 <i>:</i> 6		20 <i>:</i> 5	93 <i>:</i> 7	18 <i>:</i> 4
1 <i>:</i> 5 <i>n</i> <sup>2=5</sup>	M-PELT	16 <i>:</i> 6	89 <i>:</i> 3	16 <i>:</i> 7	20 <i>:</i> 8	93 <i>:</i> 1	18 <i>:</i> 6		21 <i>:</i> 2	94 <i>:</i> 1	18 <i>:</i> 9
	M-WBS	17 <i>:</i> 3	85 <i>:</i> 9	16 <i>:</i> 3	18 <i>:</i> 3	86 <i>:</i> 3	16 <i>:</i> 6		16 <i>:</i> 4	90 <i>:</i> 9	17 <i>:</i> 0
	M-OP	20 <i>:</i> 5	79 <i>:</i> 5	17 <i>:</i> 4	19 <i>:</i> 5	82 <i>:</i> 1	16 <i>:</i> 5		20 <i>:</i> 4	85 <i>:</i> 3	17 <i>:</i> 0
$2n^{2=5}$	M-PELT	20 <i>:</i> 2	80 <i>:</i> 3	17 <i>:</i> 1	20:0	82 <i>:</i> 7	16 <i>:</i> 7		19 <i>:</i> 7	85 <i>:</i> 5	17 <i>:</i> 0
	M-WBS	19 <i>:</i> 6	76 <i>:</i> 7	15 <i>:</i> 9	17 <i>:</i> 8	77 <i>:</i> 8	15 <i>:</i> 8		18 <i>:</i> 1	83 <i>:</i> 1	16 <i>:</i> 5

Next, we investigate the performance of our methods in the case that  $p_n > 2n^{2-5}$ . Figure S1 presents the FDR and TPR curves of MOPS, R-MOPS and M-MOPS when  $p_n$  varies in  $(2n^{2-5}; n=10)$  and the WBS algorithm is employed under Example I. Here we fix  $l_n = 10$  and the true change-point number  $K_n = 30$  and consider the error comes from N(0,1) and standardized 2(3). The FDR values of MOPS vary in an acceptable range of the target level

no matter the choice of  $p_n$  under normal error, but are slightly distorted under standardized  $^2(3)$  error. The R-MOPS is able to improve TPR and yield smaller FDR levels than MOPS due to the use of full sample information. We also observe that the M-MOPS leads to more conservative FDR levels and smaller TPR than R-MOPS because of only using half of the observations around each candidate point. That is consistent with our theoretical analysis in Proposition 1 and Theorem 3. Similar results can also be found in Figure S2.

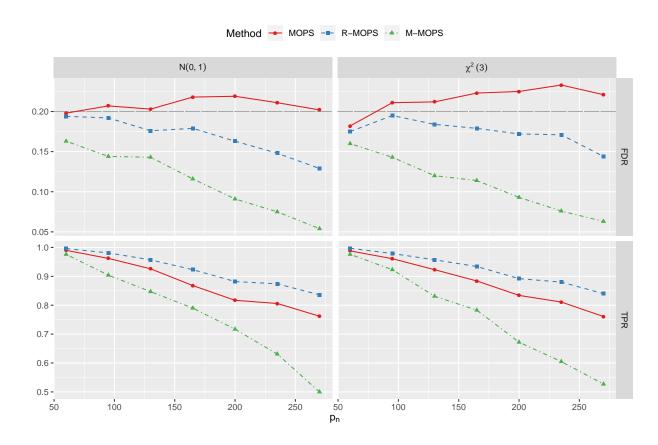


Figure S1: FDR and TPR curves against  $p_n \in (2n^{2-5}; n=10)$  of MOPS, R-MOPS and M-MOPS in conjunction with WBS algorithm when n=4096,  $K_n=30$  and SNR=1 under Example I. The  $!_n$  is xed as 10.

Figure S2 shows the FDR and TPR curves against  $!_n$  of the MOPS, R-MOPS and M-MOPS in conjunction with WBS algorithm when n = 4096,  $K_n = 10$  and  $p_n$  is fixed as  $\lfloor 2n^{2-5} \rfloor$  under Example I. It implies that all the procedures are not sensitive to the choice of  $!_n$  in terms of FDR control. Meanwhile, a large  $!_n$  could improve the detection power due

to more observations in each segment.

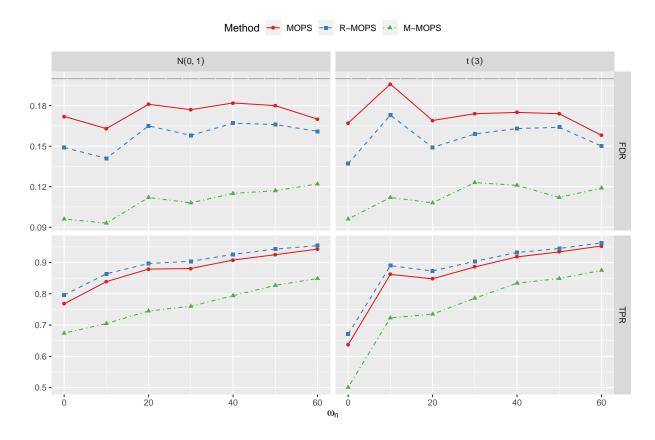


Figure S2: FDR and TPR curves against !  $_n$  of MOPS, R-MOPS and M-MOPS in conjunction with WBS algorithm when n = 4096,  $K_n = 10$  and SNR = 0.7 under Example I. The  $p_n$  is xed as  $\lfloor 2n^{2-5} \rfloor$ .

## Comparison under other models

Three other MCP models are considered, reflecting changes in different aspects such as the location and scale. Table S2 gives a summary of all three simulated models along with the associated statistics  $\bar{S}_{j}^{O}$  in constructing  $W_{j}$ .

Under multivariate mean change model (Example III), we examine the performance of the refined MOPS in conjunction with the OP and PELT algorithms. For simplicity, each dimension of the signals  $\mu_i$ 's is set as the same as the signals  $\mu_i$ 's in Example I. Two scenarios for the error distribution are considered: (i)  $\varepsilon_i \stackrel{\text{iid}}{\sim} \mathcal{N}(\mathbf{0}; -)$  with  $= (0.5^{|i-j|})_{d \times d}$ ;

Table S2: Preview of simulated models and the sample mean  $S_j^O$  of the j-th segment for the odd part. Change-points  $\hat{j}$ 's are estimated on the basis of  $\mathcal{Z}_O$ .

NO.	Model	$S^{\scriptscriptstyle O}_j$
Ш	$X_i = \mu_i + \varepsilon_i$	$\mathbf{X}_{\widehat{j}=1}^{\mathcal{O}}$
IV	$X_i \sim Multinomial(m; q_i)$	$X^{\mathcal{O}}_{\widehat{j}=1/\widehat{j}}$
V	$X_i = i''_i$	$V_{\widehat{j}_{1},\widehat{j}_{i}}^{O},\ V_{i} = \log X_{i}^{2}$

(ii)  $\varepsilon_i = ("_{i1}; \dots; "_{id})^{\top}$ , where  $"_{i1}; \dots; "_{id} \stackrel{\text{iid}}{\sim} (\ _5^2 - 5) = \sqrt{10}$ . We consider the dimension d = 5, 10 and adjust the scale parameter to  $= 9\sqrt{d}$ . Table S3 presents the results when the sample size n = 3072 and the number of change-points  $K_n = 27$ . The R-MOPS-based methods perform reasonably well in terms of FDR control and reliable TPR. In contrast, the CV-PELT results in overly conservative FDR levels across all the settings and its  $P_a$ 's are much smaller than those of R-MOPS.

Table S3: Comparison results of FDR(%), TPR(%),  $P_a$ (%) and  $\hat{K}$  when  $K_n = 27$  and n = 3072 under Example III (multivariate mean shift).

			d =			<i>d</i> = 10					
errors	Method	FDR	TPR	Pa	$\widehat{\mathcal{K}}$	FDR	TPR	Pa	Ŕ		
	RM-OP	18.5	97.1	53.5	32.9	18.9	92.9	35.0	32.1		
$arepsilon_i \sim N(0; )$	RM-PELT	18.7	97.5	54.0	32.8	18.5	92.5	33.5	31.9		
	CV-PELT	0.9	91.3	18.0	24.9	0.6	86.7	4.0	23.6		
	RM-OP	19.7	99.1	87.0	33.0	20.3	95.9	68.5	33.1		
"ij $\sim rac{rac{2}{5}-5}{\sqrt{10}}$	RM-PELT	19.5	99.0	85.5	32.7	20.8	96.2	69.5	33.3		
V 10	CV-PELT	0.8		4.5		1.7	84.1	0.0	23.1		

Further, we consider the MCP problem for multinomial distributions (Example IV), i.e.  $\mathbf{X}_i \sim \text{Multinom}(n_0; \mathbf{q}_i)$ , where the variance of the observation relies on their mean. Braun et al. (2000) integrated the problem into quasi-likelihood framework in combination with BIC to determine the number of change-points. In particular, they aimed to identify the

breaks in the probability vectors  $\mathbf{q}_l$ 's and recommended the BIC with a penalty  $n = 0.5 n^{0.23}$ , which will be seen as a benchmark for comparison in this example. To implement MOPS, we apply their algorithm in our training step, i.e., given a candidate model size  $p_n$ , we obtain the estimated change-points by constructing the statistics  $W_l$  in (5). We follow the same mechanism in Braun et al. (2000) to generate  $\mathbf{q}_l$ 's. To be specific, the initial mean vector  $\mathbf{q} = (q_1, \dots, q_d)^{\mathsf{T}}$  is given as  $q_l = U_l = \sum_{l=1}^d U_l$  for  $l = 1, \dots, d$  where  $U_l \sim \text{Uniform}(0,1)$ . The jump mean vector  $\mathbf{q}_k^* = (q_1^*, \dots, q_d^*)^{\mathsf{T}}$  for change point k is obtained by normalizing expit(logit  $q_l^* + U_l^*$ ) for  $l = 1, \dots, d$  where  $U_l^* \sim \text{Uniform}(-J,J)$  with  $J = 0.8 = \sqrt{d}$ . Table S4 reports the simulation results when n = 2048,  $K_n = 20$ ,  $n_0 \in (80,100,120)$  and d is chosen as 5 or 10. Again, our R-MOPS can successfully control the FDR at the nominal level in most cases. The BIC method appears to result in a slightly underfitting model on average. Accordingly, the BIC method delivers conservative FDR levels and it may miss some change-points due to relatively low  $P_a$ .

Table S4: Comparison results of FDR(%), TPR(%),  $P_a$ (%) and  $\widehat{K}$  between R-MOPS and BIC in conjunction with Braun et al. (2000)'s algorithm when  $K_n = 20$  and n = 2048 under Example IV.

			<i>d</i> =	5		d = 10					
$n_0$	Method	FDR	TPR	Pa	Ŕ		FDR	TPR	Pa	Ŕ	
80	R-MOPS	20.2	98.1	85.5	25.2		17.1	92.8	45.0	23.1	
	BIC	1.8	92.2	41.0	19.4		1.9	89.2	32.0	19.3	
100	R-MOPS	21.1	99.2	92.0	26.0		20.1	98.3	75.5	25.2	
	BIC	1.6	94.7	62.5	19.6		1.5	93.2	55.5	19.5	
120	R-MOPS	21.5	99.8	97.5	26.2		21.2	99.0	85.0	26.0	
	BIC	1.3	97.2	73.5	19.7		1.1	96.4	69.0	19.6	

At last, we investigate the performance of R-MOPS in conjunction with PELT under Example V when the scale signal function of  $_{i}$ 's is chosen as a piecewise constant function with values alternating between 1 and 0.5. We fix n = 4096 and show the curves of FDR, TPR and  $P_{a}$  when  $K_{n} \in [28;35]$  in Figure S3. We observe that the FDRs of R-MOPS

with PELT get closer to the target level as  $K_n$  increases, which is in accordance with the theoretical justification. Meanwhile, the CV-PELT method usually results in an underfitting model because some true change-points are not selected.

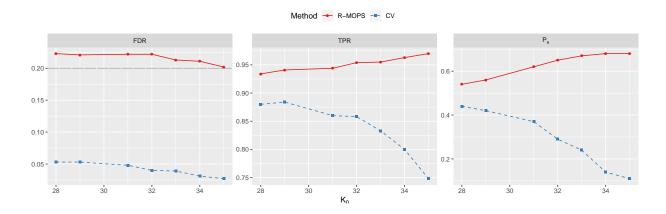


Figure S3: FDR, TPR and  $P_a$  curves against  $K_n$  between R-MOPS and CV criterion based on PELT when n = 4096 and errors are i.i.d from standardized  $t_5$  under Example V.

## Extension on controlling PFER

Table S5 reports some PFER results of the MOPS in conjunction with OP and PELT when the target PFER level  $k_0 = 1/5$  or 10. We fix the sample size n = 4096, the dimension d = 5 for multivariate data and consider that all errors are distributed from N(0/1). The validity of our MOPS approach in terms of PFER control is clear.

#### **Others**

Figure S4 displays the performance comparison under Example I with the same model setting as Section 5.1 when the target FDR level is = 0.1. The comparison results are analogous to those in nominal level = 0.2.

Table S6 presents the comparisons between our R-SaRa and dFDR-SaRa under Example I. Following the recommendation in Hao et al. (2013), we choose four thresholds  $h_1 = \lfloor 3 \log n \rfloor$ ,  $h_2 = \lfloor 5 \log n \rfloor$ ,  $h_3 = \lfloor 7 \log n \rfloor$  and  $h_4 = \lfloor 9 \log n \rfloor$  as simple competitors. It is

Table S5: PFER performance of MOPS in conjunction with OP and PELT when the target PFER level  $k_0 = 1$ ; 5 and 10 under Examples I-V.

			$K_n = 5$				$K_n = 1$	0	$K_n = 15$		
Example	$k_0$ Method	1	5	10		1	5	10	1	5	10
	M-OP	1.08	5.07	9.83		0.98	5.13	9.73	0.92	4.96	10.56
	M-PELT	0.86	4.94	9.86		0.91	5.23	10.18	1.06	5.07	10.90
11	M-OP	0.79	4.86	10.03		0.69	4.72	10.25	0.89	4.97	10.04
	M-PELT	0.74	4.14	9.57		0.77	4.93	10.36	0.66	5.05	8.58
Ш	M-OP	0.65	5.04	10.05		1.06	5.10	10.13	0.94	5.01	10.72
	M-PELT	0.67	4.78	9.83		0.83	4.87	10.27	0.72	4.91	10.60
IV	M-OP	0.81	4.13	9.18		1.01	5.16	9.93	0.97	5.13	9.75
	M-PELT	0.68	4.22	9.00		1.02	4.74	9.74	0.83	5.09	10.08
V	M-OP	0.78	5.10	9.93		0.89	5.09	10.08	1.13	5.07	10.89
	M-PELT	0.62	4.97	10.21		0.77	4.89	10.38	0.72	5.02	11.12

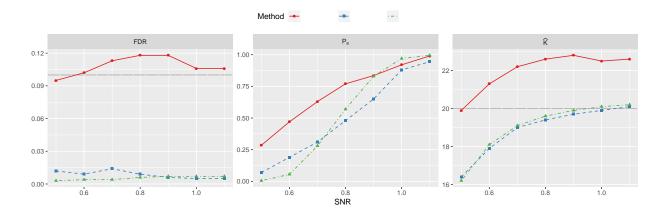


Figure S4: FDR,  $P_a$  and the average number of estimated change-points  $\hat{K}$  curves against SNR among RM-PELT, CV-PELT and FDRseg when  $K_n = 20$ , n = 2048 and the target FDR level = 0:1 under Example I.

clear that the R-MOPS performs well in terms of FDR control, but the performance of dFDR-SaRa depends on the choice of h to a large extent.

For the frequent change-point setting, Fryzlewicz (2020) proposed WBS2 detection algo-

Table S6: Comparison results of FDR(%), TPR(%),  $P_a$ (%) and  $\hat{K}$  between RM-Sara and dFDR-SaRa-h in Hao et al. (2013) when n = 10240 and SNR=0.7 under Example I.

			K <sub>n</sub> =	= 20			$K_{n} = 40$					
Errors	Method	FDR	TPR	$P_a$	Ŕ	FD	R	TPR	$P_a$	Ŕ		
N(0;1)	RM-SaRa	19.5	99.2	84.0	25.4	22	.2	99.8	92.0	52.2		
	dFDR-SaRa- $h_1$	17.1	78.2	6.5	19.2	10	.7	83.9	1.0	37.8		
	dFDR-SaRa- $h_2$	10.2	94.3	44.0	21.0	3.	0	95.9	29.0	39.6		
	dFDR-SaRa- <i>h</i> ₃	9.6	97.3	70.5	21.6	0.	2	98.3	49.5	39.4		
	dFDR-SaRa- $h_4$	3.4	99.1	90.0	20.5	0.	0	95.8	1.0	38.3		
	RM-SaRa	18.6	99.7	94.5	25.3	20	.9	99.9	96.5	51.1		
	dFDR-SaRa- $h_1$	16.8	89.2	18.5	21.6	11	.0	92.8	13.5	41.9		
$^{2}(3)$	dFDR-SaRa- <i>h</i> <sub>2</sub>	12.8	98.1	74.0	22.7	2.	0	99.3	81.0	40.5		
	dFDR-SaRa- <i>h</i> <sub>3</sub>	7.2	99.7	96.5	21.6	0.	3	99.8	92.0	40.0		
	dFDR-SaRa- $h_4$	2.6	100.0	100.0	20.6	0.	0	95.3	0.0	39.0		

rithm with threshold-based model selection criterion "Steepest Drop to Low Levels" (SDLL). We compare our procedure R-MOPS in conjunction with WBS2 to the WBS2.SDLL criterion when the "extreme teeth" example of the univariate changes in Fryzlewicz (2020) is considered. Specially, in the "extreme teeth" example, the mean i's for each observation are defined as follows: i = 0 if  $1 \le \text{mod}(i;10) \le 5$  and i = 1 if  $\text{mod}(i;10) \in \{0;6;7;8;9\}$ , and the sample size n is 1000. Two values of SNR and three error distributions including N(0;1), standardized t(3) and standardized t(3) are considered. We fix t = 1 and t = 1 in the FDRs of R-MOPS with WBS2 are still controlled, though they appear to be overly conservative. The WBS2.SDLL generally has better performances in terms of  $\hat{K}$  estimation in the most settings.

## Another real-data example: OPEC oil price

We analyze the daily Organisation of the Petroleum Exporting Countries (OPEC) Reference Basket oil prices from Jan. 6, 2003 to Dec. 16, 2020 with sample size n=4610, which is available from https://www.quandl.com. As the raw oil price series tend to ex-

Table S7: Comparisons of  $\hat{K}$ , FDR(%) and TPR(%) between R-MOPS and SDLL in conjunction with WBS2 Fryzlewicz (2020)'s \extreme.teeth" example when n = 1000,  $K_n = 199$  and three error distributions are considered. The target FDR level is = 0.2 and  $^2$  is the error variance.

			= 0:3			= 0:5					
Error	Method	$\widehat{\mathcal{K}}$	FDR	TPR	$\widehat{\mathcal{K}}$	FDR	TPR				
N(0;1)	RMOPS	193.7	7.1	90.4	160.6	10.0	72.6				
	SDLL	199.4	3.8	96.4	71.6	9.0	29.3				
<i>t</i> (3)	RMOPS	193.9	7.1	90.5	176.5	8.0	81.6				
	SDLL	209.8	7.1	97.8	221.8	19.6	89.0				
<sup>2</sup> (3)	RMOPS	193.1	7.1	90.2	167.9	8.9	76.8				
	SDLL	211.0	8.1	97.2	200.5	22.8	77.3				

hibit strong autocorrelation (Baranowski et al., 2019), we consider analyzing the log-returns  $100 \log(P_i = P_{i-1})$ , where  $P_i$  is the daily oil price. Figure S5 presents the data sequence of log-returns and its autocorrelation, indicating the correlations of log-returns are relatively weak. As Baranowski et al. (2019) pointed out that both mean and scale changes exist in the sequence, we build  $\mathbf{S}_i = (\mathbb{Z}_i : \log(\mathbb{Z}_i^2))^{\top}$  in  $W_j$  for the proposed MOPS procedure to detect changes in both the mean and variance when PELT algorithm is applied. In this study, we use the function  $\mathtt{cpt.meanvar}()$  in R package changepoint to implement the PELT algorithm and also report change-points detected by the BIC for comparison.

The BIC results in 33 change-points, while the R-MOPS with PELT yields 36 and 55 change-points when the target FDR level is 0.05 and 0.1, respectively. The locations of the change-points identified by BIC and R-MOPS with = 0.05 are given in the left panel of Figure S5. The estimated change-points of both methods largely agree each other. However, the BIC does not indicate any changes in late 2004 and early 2005 and meanwhile R-MOPS has several estimated change-points in that period. This period could potentially be related to a noticeable expansion of the production volume in the late 2004, which leads to a significant change of oil price elasticity. Thus, Murray and King (2012) called the early

#### (a) log-returns of oil prices

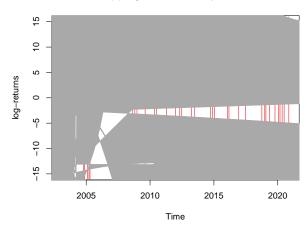


Figure S5: (a): Scatter plots of the log-returns of daily OPEC oil prices, where the blue dash and red solid lines represent the estimated change-points detected by BIC and R-MOPS with PELT algorithm under = 0.05; (b) Autocorrelation of log-returns.

2005 was oil's tipping point.

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