



# Adaptive diagnostic imaging of nonparametric regression function and its application to longitudinal data analysis

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Received 28 January 2005  
Available online 28 September 2006

## Abstract

The estimation of a regression function based on longitudinal data is considered. In the case of longitudinal data analysis, a random function, typically having a smooth trend, is often observed and a small number of time points, while in the case of nonparametric data, the random variation is small and measured on a dense grid. However, even though the mean function can be applied, a smoothing plan, as well as a number of fitting techniques, is used. In this paper, a general approach is developed for the adaptive diagnostic imaging of the mean function and covariance function obtained from noisy observations. The adaptive diagnostic imaging of the mean function is based on the principle of weighted least squares, which is a function of the local polynomial fit. The adaptive diagnostic imaging of the covariance function is based on the principle of the local profile likelihood. The adaptive diagnostic imaging of the mean function is based on the principle of weighted least squares, which is a function of the local polynomial fit. The adaptive diagnostic imaging of the covariance function is based on the principle of the local profile likelihood. The adaptive diagnostic imaging of the mean function is based on the principle of weighted least squares, which is a function of the local polynomial fit. The adaptive diagnostic imaging of the covariance function is based on the principle of the local profile likelihood.

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AMS 1991 subject classification: 62G08

Keywords: Adaptive diagnostic imaging; Covariance function; Longitudinal data; Regression function; Wiener process; Covariation

## 1. Introduction

Modern technology and advanced computing equipment have facilitated the collection and analysis of high-dimensional data, often having a large number of variables. The typical example of such data is longitudinal data, which is often collected and bounded in time. It is also called a panel variable, such as in image or geo science applications.

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When he da a a e eco ded den el o e, ime, of en b machine, he a e, picall e med f nctional o c e da a w i h one ob e ed c e o f nction pe , bjec , while in longi dinal die he epea ed mea , emen , all ake place on a fe ca e ed ob e a ional ime poin fo each bjec . A ignifican in in ic diffe ence be een wo e ing lie in he pe cep ion ha f nctional da a a e ob e ed in he con in , m w i ho noi e [2,3], he ea longi dinal da a a e ob e ed a pa el di ib ed im e poin and a e of en , bjec o e pe imen al e o [4]. Ho we e , in p ac ice f nctional da a a e anal ed af e moohing noi ob e a ion [10], whic indica e ha he diffe ence be een wo da a pe ela ed o he wa in whic h a p oblem i pe cei ed a e a g abl mo e concep al han ac al. The efo e in hi pape , ke nel ba ed eg e ion e, ima o ob ained f om ob e a ion a di c e e, im e poin con amina ed w i h mea , emen e o , a he han ob e a ion in he con in , m, a e con ide ed fo he e eali ic ea on . In he con e of ke nel ba ed nonpa ame ic eg e ion, he effec of ampling plan on he a i cal e, ima o a e al o in e, iga ed.

A a l i e a , e ha been de eloped in he pa decade on he ke nel ba ed eg e ion fo independen and iden icall di ib ed da a , fo mma , ee Fan and Gijbel [5]. The e ha been , b an al ecen in e e in e ending he e i ing a mp o ic e , l o f nctional o longi dinal da a [8,11,14,13,9]. The i , e ca ed b he w i hin , bjec co ela ion a e igo o 1 add e ed in hi pape . Ha , and Weh l [8] , died he Ga e M lle e, ima o of he mean f nction fo epea ed mea , emen ob e ed on a eg la g id b a , ming a iona co elation , c e, and howed ha he infl ence of he w i hin , bjec co ela ion on he a mp o ic a iance i of malle o de compa ed o he anda d a e ob ained f om independen da a and w ill di appa wh en he co ela ion f nction i diffe en iable a e o. O a mp o ic di ib ion e , l i in fac con i en w i h ha in Ha , and Weh l [8] and applicable fo gene al co a iance , c e w i ho , a iona a , mp ion. Thi p oblem a al o di c ed b Sani w ali and Lee [12] and Lin and Ca oll [9], he e he , ed he he i ic a g men of he local p ope of local pol nomial e, ima ion and in , i i el igno ed he w i hin , bjec co ela ion while de i ing he a mp o ic a iance . Thi pape de i e app op ia e condion ha a e e q i ed fo he alidi of he local p ope of ke nel pe e, ima o ob ained f om longi dinal o f nctional da a . The e condion al o p o ide p ac ical g ideline fo a io ampling p oced e .

The con ib ion of hi pape i , he de i a ion of gene al a mp o ic di ib ion e , l in bo h one-dimen ional and wo-dimen ional moohing con e fo eal al ed f nction w i h a g men whic ha e f nctional fo med b w eigh ed a e age of longi dinal o f nctional da a . The e a mp o ic no mal i e , l a e compa able o he ke nel ba ed e, ima o of he mean and co a iance f nction , whic h ield a mp o ic no mal di ib ion of he e e, ima o . In pa ic la o he be of o knowle dge, no a mp o ic di ib ion e , l a e a ailable p o da e fo nonpa ame ic e, ima ion of co a iance f nction ob ained f om longi dinal o f nctional da a con amina ed w i h mea , emen e o . B compa i on, Hall e al. [6,7] in e iga ed a mp o ic p ope ie of nonpa ame ic ke nel e, ima o of a oco a iance, he e he mea , emen e onl ob e ed f om a ingle a iona ocha ic p oce o andom field. Al ho gh he a mp o ic di ib ion a e de i ed fo andom de ign in hi pape , he a g men can be e ended o fi ed de ign and o he ampling plan w i h app op ia e modifica ion , and a mp o ic bia and a iance e m can al o be ob ained in imila manne . Thi w ill p o ide heo e ical ba i and p ac ical g idance fo he nonpa ame ic anal i off f nctional o longi dinal da a w i h impo an po en i al applica ion whic ha e ba ed on he a mp o ic di ib ion . T pical e ample incl de he con , c ion of a mp o ic confidence band fo eg e ion f nction and confidence egi on

for confidence interval, and also for the estimation of bandwidth. The application of the mean square error of the approximation of the mean function is independent of the dimension of the data. It can be applied for the modeling of longitudinal data, including kernel-based estimation of the mean function.

The remainder of the paper is organized as follows. In Section 2 we describe the general algorithmic procedure of one- and two-dimensional nonparametric modeling. The estimation of the mean function is applied to common design kernel-based estimation of the mean function. The estimation of the mean function is described in Section 3. Estimation of the mean function in Section 4. A simulation study is performed to evaluate the performance of the proposed method in Section 5, while discussion, including potential applications of the estimation, is provided in Section 6.

## 2. General results of asymptotic distributions for random design

In this section we will define general functional approximation based on kernel-based estimation of the mean function. The individual general functional approximation includes the mean function, common design kernel-based estimation of the mean function, a special case, such as Gaussian and local polynomial estimation, etc. Since Nadaraya-Watson and local polynomial estimation are more popular, they are mentioned here. The mean function behavior in terms of bias and variance for independent data has been studied by Ghosh (1998), who died in 2004. However, for longitudinal data, parametric methods have been developed in the literature. The lack of a general theory of the mean function of longitudinal data is an additional motivation for the definition of the two-dimensional nonparametric mean function. It can be applied to the estimation of the mean function of the data. The general algorithmic procedure of one- and two-dimensional nonparametric modeling is described in Section 3, the estimation of the mean function is applied to common design kernel-based estimation of the mean function. The estimation of the mean function is described in Section 4. A simulation study is performed to evaluate the performance of the proposed method in Section 5, while discussion, including potential applications of the estimation, is provided in Section 6.

We first consider random design estimation while the sampling plan is defined in Section 4. In classical longitudinal data, mean estimation is often ended to be on a regular grid. However, once individual data points are added sequentially, all become part of the new observation set. The difference between mean estimation and mean estimation is the number of repeated observations. This sampling

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a iance  $\sigma^2$ ,

$$Y_{ij} = X_i(T_{ij}) + \varepsilon_{ij} = \mu(T_{ij}) + \sum_{k=1}^{\infty} \xi_{ik} \phi_k(T_{ij}) + \varepsilon_{ij}, \quad T_{ij} \in \mathcal{T}, \quad (1)$$

the  $E\varepsilon_{ij} = 0$ ,  $\text{var}(\varepsilon_{ij}) = \sigma^2$ , and the n mbe of ob e a ion,  $N_i(n)$  depending on he ample i en, a e con ide ed andom. We make, he following a , mp ion,

(A1.1) The n mbe of ob e a ion  $N_i(n)$  made fo he i h , bjec o cl e,  $i = 1, \dots, n$ , i a . . i.i.d. wh N\_i(n) ~ N(n), the N(n) > 0 i a po i i e in ege - al ed andom a iable wh lim , p\_{n \rightarrow \infty} EN(n)^2/[EN(n)]^2 < \infty and lim , p\_{n \rightarrow \infty} EN(n)^4/EN(n)EN(n)^3 < \infty.

In he eq el he dependence of  $N_i(n)$  and  $N(n)$  on he ample i en i , pp e ed fo implici ; i.e.,  $N_i = N_i(n)$  and  $N(n) = N$ . The ob e a ion, imme and mea , emen a ea , med o be independent of he n mbe of mea , emen , i.e., fo an , b e J\_i \subseteq \{1, \dots, N\_i\} and fo all  $i = 1, \dots, n$ ,

(A1.2) ( $\{T_{ij} : j \in J_i\}$ ,  $\{Y_{ij} : j \in J_i\}$ ) i independent of  $N_i$ .

W i ing  $T_i = (T_{i1}, \dots, T_{iN_i})^T$  and  $Y_i = (Y_{i1}, \dots, Y_{iN_i})^T$ , i i ea , o ee ha he i ple  $\{T_i, Y_i, N_i\}$  a e i.i.d..

## 2.1. Asymptotic normality of one-dimensional smoother

To a , me app op ia e eg la i cond i on ha a e , ed o de i e a mp o ic p ope ie , we define a new pe of con in i ha diffe f om ho e wh ch a e commonl ed. We a ha a eal f nc ion  $f(x, y) : \mathbb{R}^{p+q} \rightarrow \mathbb{R}$  i con in o on  $x \in A \subseteq \mathbb{R}^p$ , nifo ml in  $y \in \mathbb{R}^q$ , p o ided ha fo an  $x \in A$  and  $\varepsilon > 0$ , he e e i a neighbor hood of  $x$  no depending on y, a ing  $U(x) \subseteq \mathbb{R}^p$ , ch ha | $f(x', y) - f(x, y)| < \varepsilon$  fo all  $x' \in U(x)$  and  $y \in \mathbb{R}^q$ .

Fo andom de ign,  $(T_{ij}, Y_{ij})$  a e a , med o ha e he iden ical di ib ion a  $(T, Y)$  wh join den i g(t, y). A , me ha he ob e a ion, imme  $T_{ij}$  a e i.i.d. wh he ma ginal den i f(t), b , dependence i allo ed among  $Y_{ij}$  and  $Y_{ik}$  ha a e ob e a ion made fo he ame , bjec o cl e. Al o deno e he join den i of  $(T_j, T_k, Y_j, Y_k)$  b g\_2(t\_1, t\_2, y\_1, y\_2), wh e j \neq k. Le v, k be gi en in ege , wh h 0 \leq v < k. We a , me eg la i cond i on fo he ma ginal and join den i ie , f(t), g(t, y), g\_2(t\_1, t\_2, y\_1, y\_2) and he mean f nc ion of he , nde l ing p oce  $X(t)$ , i.e.,  $E[X(t)] = \mu(t)$ , wh e pec o a neighbor hood of a in e io poin t \in \mathcal{T}, a , ming ha he e i a neighbor hood  $U(t)$  of t , ch ha :

(B1.1)  $\frac{d^k}{du^k} f(u)$  e i , and i con in o on  $u \in U(t)$ , and  $f(u) > 0$  fo  $u \in U(t)$ ;

(B1.2)  $g(u, y)$  i con in o on  $u \in U(t)$ , nifo ml in  $y \in \mathbb{R}$ ;  $\frac{d^k}{du^k} g(u, y)$  e i , and i con in o on  $u \in U(t)$ , nifo ml in  $y \in \mathbb{R}$ ;

(B1.3)  $g_2(u, v, y_1, y_2)$  i con in o on  $(u, v) \in U(t)^2$ , nifo ml in  $(y_1, y_2) \in \mathbb{R}^2$ ;

(B1.4)  $\frac{d^k}{du^k} \mu(u)$  e i , and i con in o on  $u \in U(t)$ .

Le  $K_1(\cdot)$  be nonnega i e , ni a ia e ke nel f nc ion in one-dimen ional moo hing. The a , mp ion fo ke nel  $K_1 : \mathbb{R} \rightarrow \mathbb{R}$  a ea follo . We a , ha a , ni a ia e ke nel f nc ion  $K_1$  i of o de (v, k), if

$$\int u^\ell K_1(u) du = \begin{cases} 0, & 0 \leq \ell < k, \ell \neq v, \\ (-1)^v v!, & \ell = v, \\ \neq 0, & \ell = k, \end{cases} \quad (2)$$

(B2.1)  $K_1$  is compact, bounded,  $\|K_1\|^2 = \int K_1^2(u) du < \infty$ ;

(B2.2)  $K_1$  is a kernel function of order  $(v, \ell)$ .

Let  $b = b(n)$  be a sequence of bandwidths,  $b \rightarrow 0$ , as  $n \rightarrow \infty$ , and  $v \geq 1$ . We denote a  $mpo$ ic condition  $b \rightarrow 0$ ,  $n(EN)b^{v+1} \rightarrow \infty$ ,  $b(EN) \rightarrow 0$ , and  $n(EN)b^{2k+1} \rightarrow d^2$  for some  $d$  with  $0 \leq d < \infty$ .

One could see in the proof of Theorem 1, the assumption (B3) combined with (A1.1) provides the condition, which holds for longitudinal or functional data, the performance of  $\hat{\psi}_\lambda$  being controlled by the local properties of the kernel function.

Let  $\{\psi_\lambda\}_{\lambda=1,\dots,l}$  be a collection of real functions  $\psi_\lambda : \mathbb{R}^2 \rightarrow \mathbb{R}$ , which satisfy:

(B4.1)  $\psi_\lambda(t, y)$  are continuous on  $\{t\}$ , uniformly in  $y \in \mathbb{R}$ ;

(B4.2)  $\frac{d^k}{dt^k}\psi_\lambda(t, y)$  exist for all arguments  $(t, y)$  and are continuous on  $\{t\}$ , uniformly in  $y \in \mathbb{R}$ .

Then we define the general weighted average

$$\Psi_{\lambda n} = \frac{1}{nENb^{v+1}} \sum_{i=1}^n \sum_{j=1}^{N_i} \psi_\lambda(T_{ij}, Y_{ij}) K_1\left(\frac{t - T_{ij}}{b}\right), \quad \lambda = 1, \dots, l.$$

and

$$\mu_\lambda = \mu_\lambda(t) = \frac{d^v}{dt^v} \int \psi_\lambda(t, y) g(t, y) dy, \quad \lambda = 1, \dots, l.$$

Let

$$\sigma_{\kappa\lambda} = \sigma_{\kappa\lambda}(t) = \int \psi_\kappa(t, y) \psi_\lambda(t, y) g(t, y) dy \|K_1\|^2, \quad 1 \leq \lambda, \kappa \leq l,$$

and  $H : \mathbb{R}^l \rightarrow \mathbb{R}$  be a function with continuous first order derivatives. We denote the gradient vector  $((\partial H/\partial x_1)(v), \dots, (\partial H/\partial x_l)(v))^\top$  by  $DH(v)$  and  $\bar{N} = \sum_{i=1}^n N_i/n$ .

**Theorem 1.** If the assumptions (A1.1), (A1.2) and (B1.1)–(B4.2) hold, then

$$\begin{aligned} \sqrt{n\bar{N}b^{2v+1}}[H(\Psi_{1n}, \dots, \Psi_{ln}) - H(\mu_1, \dots, \mu_l)] &\xrightarrow{\mathcal{D}} \mathcal{N}(\beta, [DH(\mu_1, \dots, \mu_l)]^T \\ &\Sigma [DH(\mu_1, \dots, \mu_l)]), \end{aligned} \quad (3)$$

where

$$\beta = \frac{(-1)^k d}{k!} \int u^k K_1(u) du \sum_{\lambda=1}^l \frac{\partial H}{\partial \mu_\lambda} \{(\mu_1, \dots, \mu_l)^T\} \frac{d^{k-v}}{dt^{k-v}} \mu_\lambda(t), \quad \Sigma = (\sigma_{\kappa\lambda})_{1 \leq \kappa, \lambda \leq l}.$$

**Proof.** It is seen that  $\bar{N}$  can be replaced with  $EN$  by Theorem 1. We note how

$$\sqrt{n(EN)b^{2v+1}}[H(E\Psi_{1n}, \dots, E\Psi_{ln}) - H(\mu_1, \dots, \mu_l)] \longrightarrow \beta. \quad (4)$$

Since (A1.1) and (A1.2) hold, and  $K_1$  is of order  $(v, k)$ , using Taylor expansion one obtain

$$\begin{aligned}
 E\Psi_{\lambda n} &= \frac{1}{nb^{v+1}} E \left\{ \sum_{i=1}^n \frac{1}{EN} \sum_{j=1}^{N_i} \psi_\lambda(T_{ij}, Y_{ij}) K_1 \left( \frac{t - T_{ij}}{b} \right) \right\} \\
 &= \frac{1}{b^{v+1} EN} E \left\{ \sum_{j=1}^N E \left[ \psi_\lambda(T_j, Y_j) K_1 \left( \frac{t - T_j}{b} \right) \middle| N \right] \right\} \\
 &= \frac{1}{b^{v+1}} E \left\{ \psi_\lambda(T, Y) K_1 \left( \frac{t - T}{b} \right) \right\} \\
 &= \mu_\lambda + \frac{(-1)^k}{k!} \int u^k K_1(u) du \frac{d^{k-v}}{dt^{k-v}} \mu_\lambda(t) b^{k-v} + o(b^{k-v}). \tag{5}
 \end{aligned}$$

Then (4) follows from an  $l$ -dimensional Taylor expansion of  $H$  of order 1 and  $(\mu_1, \dots, \mu_l)^T$ , completed with (5). If we can show

$$\sqrt{n(EN)b^{2v+1}}[(\Psi_{1n}, \dots, \Psi_{ln})^T - (E\Psi, \dots, E\Psi_{ln})^T] \xrightarrow{\mathcal{D}} \mathcal{N}(0, \Sigma), \tag{6}$$

in analogy to Bhattacharya and Mukherjee [1], and combining of  $DH$  of  $(\mu_1, \dots, \mu_l)^T$  and applying similar arguments used in (5), we find  $DH(E\Psi_{1n}, \dots, E\Psi_{ln}) \rightarrow DH(\mu_1, \dots, \mu_l)$ . Then Cauchy-Wold theorem yield

$$\begin{aligned}
 \sqrt{n(EN)b^{2v+1}}[H(\Psi_{1n}, \dots, \Psi_{ln}) - H(E\Psi, \dots, E\Psi_{ln})] &\xrightarrow{\mathcal{D}} \mathcal{N}(0, DH(\mu_1, \dots, \mu_l)^T \\
 &\quad \Sigma DH(\mu_1, \dots, \mu_l)), \tag{7}
 \end{aligned}$$

combined with (4), leading to (3).

It remains to prove (6). Owing to (A1.1) and (A1.2), one has

$$\begin{aligned}
 &n(EN)b^{2v+1} \text{cov}(\Psi_{\lambda n}, \Psi_{\kappa n}) \\
 &= \frac{1}{b} E \left\{ \frac{1}{EN} \left[ \sum_{j=1}^N \psi_\lambda(T_j, Y_j) K_1 \left( \frac{t - T_j}{b} \right) \right] \left[ \sum_{k=1}^N \psi_\kappa(T_k, Y_k) K_1 \left( \frac{t - T_k}{b} \right) \right] \right\} \\
 &\quad - \frac{EN}{b} E \left[ \frac{1}{EN} \sum_{j=1}^N \psi_\lambda(T_j, Y_j) K_1 \left( \frac{t - T_j}{b} \right) \right] \\
 &\quad \times E \left[ \frac{1}{EN} \sum_{k=1}^N \psi_\kappa(T_k, Y_k) K_1 \left( \frac{t - T_k}{b} \right) \right] \\
 &\equiv I_1 - I_2.
 \end{aligned}$$

In order to obtain the expression of  $I_2 = O(b) = o(1)$  from the definition of (5). For  $I_1$ , it can be written as

$$I_1 = \frac{1}{b} E \left[ \frac{1}{EN} \sum_{j=1}^N \psi_\lambda(T_j, Y_j) \psi_\kappa(T_j, Y_j) K_1^2 \left( \frac{t - T_j}{b} \right) \right]$$

$$+ \frac{1}{b} E \left[ \frac{1}{EN} \sum_{1 \leq j \neq k \leq N} \psi_\lambda(T_j, Y_j) \psi_\kappa(T_k, Y_k) K_1 \left( \frac{t - T_j}{b} \right) K_1 \left( \frac{t - Y_k}{b} \right) \right]$$

$$\equiv Q_1 + Q_2.$$

Applying (A1.1) and (A1.2), one has

$$Q_1 = \frac{1}{b} E \left\{ \frac{1}{EN} \sum_{j=1}^N E \left[ \psi_\lambda(T_j, Y_j) \psi_\kappa(T_j, Y_j) K_1^2 \left( \frac{t - T_j}{b} \right) \middle| N \right] \right\}$$

$$= \frac{1}{b} E \left[ \psi_\lambda(t, Y) \psi_\kappa(t, Y) K_1^2 \left( \frac{t - Y}{b} \right) \right] = \sigma_{\lambda\kappa} + o(1).$$

Then (4) will hold, observing (A1.1) and the following arguments, we have a simple proof of the local polynomial kernel-based estimator's consistency of the partial derivative estimation in longitudinal data.

$$Q_2 = \frac{1}{bEN} E \left\{ \sum_{1 \leq j \neq k \leq N} E \left[ \psi_\lambda(T_j, Y_j) \psi_\kappa(T_k, Y_k) K_1 \left( \frac{t - T_j}{b} \right) K_1 \left( \frac{t - T_k}{b} \right) \middle| N \right] \right\}$$

$$= \frac{EN(N-1)}{bEN} E \left[ \psi_\lambda(T_1, Y_1) \psi_\kappa(T_2, Y_2) K_1 \left( \frac{t - T_1}{b} \right) \right] K_1 \left( \frac{t - T_2}{b} \right)$$

$$= \frac{bEN(N-1)}{EN} \int_{\mathbb{R}^4} \psi_\lambda(t - ub, y_1) \psi_\kappa(t - vb, y_2) K_1(u) K_2(v)$$

$$\times g_2(t - ub, t - vb, y_1, y_2) du dv dy_1 dy_2$$

$$= \frac{bEN(N-1)}{EN} \int_{\mathbb{R}^2} \psi_\lambda(t, y_1) \psi_\kappa(t, y_2) g_2(t, t, y_1, y_2) dy_1 dy_2 + o(b) = o(1),$$

i.e., the partial derivative estimation can be ignored while dealing with the asymptotic variance.  $\square$

## 2.2. Asymptotic normality of two-dimensional smoother

The general asymptotic error can be expanded into a two-dimensional smoothing. Let  $(v, k)$  denote the multi-index  $v = (v_1, v_2)$  and  $k = (k_1, k_2)$ , where  $|v| = v_1 + v_2$  and  $|k| = k_1 + k_2$ . In two-dimensional smoothing, more generally, a dimension needed for joint dimension. Let  $f_2(s, t)$  be the joint density of  $(T_j, T_k)$ , and  $g_4(s, t, s', t', y_1, y_2, y'_1, y'_2)$  be the joint density of  $(T_j, T_k, T_{j'}, T_{k'}, Y_j, Y_k, Y_{j'}, Y_{k'})$  where  $j \neq k$ ,  $(j, k) \neq (j', k')$ . Denote the covariance surface by  $C(s, t) = \text{cov}(X(T_j), X(T_k)|T_j = s, T_k = t)$ . The following equality condition also holds, namely,  $U(s, t) \in \text{some neighborhood of } \{(s, t)\}$ ,

$$(C1.1) \quad \frac{d^{|k|}}{du^{k_1} dv^{k_2}} f_2(u, v) \text{ exists and is continuous on } (u, v) \in U(s, t), \text{ and } f_2(u, v) > 0 \text{ for } (u, v) \in U(s, t);$$

- (C1.2)  $g_2(u, v, y_1, y_2)$  is compactly supported on  $(u, v) \in U(s, t)$ , and its second derivatives  $\frac{d^{|k|}}{du^{k_1} dv^{k_2}}$  of  $g_2(u, v, y_1, y_2)$  exist and are compactly supported on  $(u, v) \in U(s, t)$ , and its second derivatives  $\frac{d^{|k|}}{du^{k_1} dv^{k_2}}$  of  $g_2(u, v, y_1, y_2)$  exist and are compactly supported on  $(y_1, y_2) \in \mathbb{R}^2$ ;
- (C1.3)  $g_4(u, v, u', v', y_1, y_2, y'_1, y'_2)$  is compactly supported on  $(u, v, u', v') \in U(s, t)^2$ , and its second derivatives  $\frac{d^{|k|}}{du^{k_1} dv^{k_2}}$  of  $g_4(u, v, u', v', y_1, y_2, y'_1, y'_2)$  exist and are compactly supported on  $(y_1, y_2, y'_1, y'_2) \in \mathbb{R}^4$ ;
- (C1.4)  $\frac{d^{|k|}}{du^{k_1} dv^{k_2}} C(u, v)$  exists and is compactly supported on  $(u, v) \in U(s, t)$ .

Let  $K_2$  be a nonnegative function belonging to the  $\mathbb{R}^2$ -dimensional mollifying function space. Then we can decompose  $K_2$  into a sum of two parts: one part is a compactly supported function with  $\|K_2\|^2 = \int_{\mathbb{R}^2} K_2^2(u, v) du dv < \infty$ , and the other part is a smooth function with a compact support.

- (C2.1)  $K_2$  is compactly supported, and  $\|K_2\|^2 = \int_{\mathbb{R}^2} K_2^2(u, v) du dv < \infty$ , and it is smooth and has a compact support.
- (C2.2)  $K_2$  is a kernel function of order  $(|\mathbf{v}|, |\mathbf{k}|)$ , i.e.,

$$\sum_{\ell_1+\ell_2=|\mathbf{l}|} \int_{\mathbb{R}^2} u^{\ell_1} v^{\ell_2} K_2(u, v) du dv = \begin{cases} 0, & 0 \leq |\mathbf{l}| < |\mathbf{k}|, |\mathbf{l}| \neq |\mathbf{v}|, \\ (-1)^{|\mathbf{v}|} |\mathbf{v}|!, & |\mathbf{l}| = |\mathbf{v}|, \\ \neq 0, & |\mathbf{l}| = |\mathbf{k}|. \end{cases} \quad (8)$$

Let  $h = h(n)$  be a sequence of bandwidths, and  $h$  is in the  $\mathbb{R}^2$ -dimensional mollifying function space. While it is possible that the bandwidth  $h$  is too large, it may be difficult to choose  $h$  such that the error term  $\epsilon$  is small. Since we will focus on the estimation of the covariance function  $h$  in the  $\mathbb{R}^2$ -dimensional space, we will focus on the identification of the bandwidth  $h$  for the  $\mathbb{R}^2$ -dimensional space. The approach is developed as  $n \rightarrow \infty$  as follows:

- (C3)  $h \rightarrow 0$ ,  $nEN^2h^{|\mathbf{v}|+2} \rightarrow \infty$ ,  $hEN^3 \rightarrow 0$ , and  $nE[N(N-1)]h^{2|\mathbf{k}|+2} \rightarrow e^2$  for some  $0 \leq e < \infty$ .

Similarly to the one-dimensional mollifying case, a compact operator (C3) and (A1.1) guarantees the local properties of the bandwidth  $h$  being bounded and the convergence of the function  $\phi_\lambda$  to the identity function.

Let  $\{\phi_\lambda\}_{\lambda=1,\dots,l}$  be a collection of real functions  $\phi_\lambda : \mathbb{R}^4 \rightarrow \mathbb{R}$ ,  $\lambda = 1, \dots, l$ , satisfying

- (C4.1)  $\phi_\lambda(s, t, y_1, y_2)$  is compactly supported on  $\{(s, t)\}$ , and its second derivatives  $\frac{d^{|k|}}{ds^{k_1} dt^{k_2}}$  of  $\phi_\lambda(s, t, y_1, y_2)$  exist and are compactly supported on  $(y_1, y_2) \in \mathbb{R}^2$ ;
- (C4.2)  $\frac{d^{|k|}}{ds^{k_1} dt^{k_2}} \phi_\lambda(s, t, y_1, y_2)$  exists for all arguments  $(s, t, y_1, y_2)$  and is compactly supported on  $\{(s, t)\}$ , and its second derivatives  $\frac{d^{|k|}}{ds^{k_1} dt^{k_2}}$  of  $\phi_\lambda(s, t, y_1, y_2)$  exist and are compactly supported on  $(y_1, y_2) \in \mathbb{R}^2$ .

Then the general weighted average of the  $\mathbb{R}^2$ -dimensional mollifying functions is defined by  $1 \leq \lambda \leq l$ ,

$$\Phi_{\lambda n} = \Phi_{\lambda n}(t, s) = \frac{1}{nE[N(N-1)]h^{|\mathbf{v}|+2}} \sum_{i=1}^n \sum_{1 \leq j \neq k \leq N_i} \phi_\lambda(T_{ij}, T_{ik}, Y_{ij}, Y_{ik})$$

$$\times K_2 \left( \frac{s - T_{ij}}{h}, \frac{t - T_{ik}}{h} \right).$$

Let

$$m_\lambda = m_\lambda(s, t) = \sum_{v_1+v_2=|\mathbf{v}|} \frac{d^{|\mathbf{v}|}}{ds^{v_1} dt^{v_2}} \int_{\mathbb{R}^2} \phi_\lambda(s, t, y_1, y_2) g_2(s, t, y_1, y_2) dy_1 dy_2, \quad 1 \leq \lambda \leq l,$$

and

$$\omega_{\kappa\lambda} = \omega_{\kappa\lambda}(s, t) = \int_{\mathbb{R}^2} \phi_{\kappa}(s, t, y_1, y_2) \phi_{\lambda}(s, t, y_1, y_2) g_2(s, t, y_1, y_2) dy_1 dy_2 \|K_2\|^2,$$

$$1 \leq \kappa, \lambda \leq l,$$

and  $H : \mathbb{R}^l \rightarrow \mathbb{R}$  is a function which contains or finite degrees of freedom and is a p.e.o.l defined.

**Theorem 2.** If assumptions (A1.1), (A1.2) and (C1.1)–(C4.2) hold, then

$$\sqrt{n\bar{N}(\bar{N}-1)h^{2|\nu|+2}}[H(\Phi_{1n}, \dots, \Phi_{ln}) - H(m_1, \dots, m_l)]$$

$$\xrightarrow{\mathcal{D}} \mathcal{N}(\gamma, [DH(m_1, \dots, m_l)]^T \Omega [DH(m_1, \dots, m_l)]), \quad (9)$$

where

$$\begin{aligned} \gamma &= \frac{(-1)^{|k|} e}{|k|!} \sum_{\lambda=1}^l \left\{ \sum_{k_1+k_2=|k|} \int_{\mathbb{R}^2} u^{k_1} v^{k_2} K_2(u, v) du dv \frac{d^{|k|}}{ds^{k_1} dt^{k_2}} \right. \\ &\quad \times \left. \int_{\mathbb{R}^2} \phi_{\lambda}(s, t, y_1, y_2) g_2(s, t, y_1, y_2) dy_1 dy_2 \right\} \\ &\quad \times \left\{ \frac{\partial H}{\partial m_{\lambda}}(m_1, \dots, m_l)^T \right\}, \end{aligned}$$

$$\Omega = (\omega_{\kappa\lambda})_{1 \leq \kappa \leq l}.$$

The proof of Theorem 2 is similar to that of Theorem 1 with appropriate modification which are omitted for brevity.

### 3. Applications to nonparametric regression estimators for functional or longitudinal data

Although the theory of kernel-based estimation has been developed in literature, Nadaraya-Watson and local polynomial, especially local linear estimation, have been commonly used non-parametric modeling techniques in longitudinal functional data analysis. Despite various methods, the asymptotic behavior in terms of bias and variance of the estimators have not been well understood for i.i.d. data. Especially, a comparison between local linear and local quadratic methods for functional data has not been made. The focus in this section is to apply the asymptotic theory of Nadaraya-Watson and local linear estimation to functional data and compare their performance, focusing on the mean function.

#### 3.1. Asymptotic distributions of mean estimators

We apply Theorem 1 to the local quadratic estimation of the common local Nadaraya-Watson kernel estimator  $\hat{\mu}_N(t)$  and local linear estimator  $\hat{\mu}_L(t)$  for functional/longitudinal data.

da a:

$$\hat{\mu}_N(t) = \left[ \sum_{i=1}^n \sum_{j=1}^{N_i} K_1\left(\frac{t - T_{ij}}{b}\right) Y_{ij} \right] \Bigg/ \left[ \sum_{i=1}^n \sum_{j=1}^{N_i} K_1\left(\frac{t - T_{ij}}{b}\right) \right], \quad (10)$$

$$\hat{\mu}_L(t) = \hat{\alpha}_0(t) = \min_{(\alpha_0, \alpha_1)} \left\{ \sum_{i=1}^n \sum_{j=1}^{N_i} K_1\left(\frac{t - T_{ij}}{b}\right) [Y_{ij} - (\alpha_0 + \alpha_1(T_{ij} - t))]^2 \right\}. \quad (11)$$

**Corollary 1.** If assumptions (A1.1), (A1.2), and (B1.1)–(B3) hold with  $v = 0$  and  $k = 2$ , then

$$\sqrt{n\bar{N}b}[\hat{\mu}_N(t) - \mu(t)] \xrightarrow{\mathcal{D}} \mathcal{N}\left(\frac{d}{2} \frac{\mu^{(2)}(t)f(t) + 2\mu^{(1)}(t)f^{(1)}(t)}{f(t)} \sigma_{K_1}^2, \frac{\text{var}(Y|T=t)\|K_1\|^2}{f(t)}\right), \quad (12)$$

where  $d$  is as in (B3),  $\sigma_{K_1}^2 = \int u^2 K_1(u) du$  Tm((()T/F295

He e  $w_{ij} = K_1((t - T_{ij})/b)/(nb)$ , he e  $K_1$  i a ke nel f nç ion of o de (0, 2), a i f ing (B2.1) and (B2.2), and  $\hat{\alpha}_1(t)$  i an e ima o fo he fi de i a i e  $\mu'(t)$  of  $\mu$  a t.

Ob e ing ha Co olla 1 implie  $\hat{\mu}_N(t) \xrightarrow{p} \mu(t)$ , le  $\hat{f}(t) = \sum_i \sum_j w_{ij}/N_i$ , i i ea ho  $\hat{f}(t) \xrightarrow{p} f(t)$  in analog o Co olla 1. We p oceed o ho  $\hat{\alpha}_1(t) \xrightarrow{p} \mu'(t)$ . Deno e  $\sigma_{K_1}^2 = \int u^2 K_1(u) du$ , he ke nel f nç ion  $\tilde{K}_1(t) = -t K_1(t)/\sigma_{K_1}^2$ , and define  $\Psi_{\lambda n}$ ,  $1 \leq \lambda \leq 3$  b  $\psi_1(u, y) = y$ ,  $\psi_2(u, y) \equiv 1$ ,  $\psi_3(u, y) = u - t$ . Ob e e ha  $\tilde{K}_1$  i of o de (1, 3),  $\hat{f}(t) \xrightarrow{p} f(t)$ , and define

$$\tilde{H}(x_1, x_2, x_3) = \frac{x_1 - x_2 \hat{\mu}_N(t)}{x_3 - bx_2^2/\hat{f}(t) \cdot \sigma_{K_1}^2} \quad \text{and} \quad H(x_1, x_2, x_3) = \frac{x_1 - x_2 \mu(t)}{x_3}.$$

Then

$$\begin{aligned} \hat{\alpha}_1(t) &= \tilde{H}(\Psi_{1n}, \Psi_{2n}, \Psi_{3n}) \\ &= \left[ H(\Psi_{1n}, \Psi_{2n}, \Psi_{3n}) + \frac{\Psi_{2n}(\mu(t) - \hat{\mu}_N(t))}{\Psi_{3n}} \right] \frac{\Psi_{3n}}{\Psi_{3n} + b^2 \Psi_{2n}^2 / \hat{f}(t) \cdot \sigma_{K_1}^2}. \end{aligned}$$

No e ha  $\mu_1 = (\mu' f + mf')(t)$ ,  $\mu_2 = f'(t)$ , and  $\mu_3 = f(t)$ , impl ing  $\Psi_{\lambda n} - \mu_\lambda = O_p(1/\sqrt{n\bar{N}b^3})$ , fo  $\lambda = 1, 2, 3$ , b Theo em 1. U ing Slutsky's Theo em,  $|\tilde{H}(\Psi_{1n}, \Psi_{2n}, \Psi_{3n}) - \mu'(t)| = O_p(1/\sqrt{n\bar{N}b^3})$  follo .

Fo he a mp o ic di ib ion of  $\hat{\mu}_L$ , no e ha

$$\hat{\mu}_L(t) = \frac{\sum_i \frac{1}{EN} \sum_j w_{ij} Y_{ij} - \sum_i \frac{1}{EN} \sum_j w_{ij} (T_{ij} - t) \hat{\alpha}_1(t)}{\sum_i \frac{1}{EN} \sum_j w_{ij}}.$$

Con ide ing  $\sqrt{n\bar{N}b} \sum_i \frac{1}{EN} \sum_j w_{ij} (T_{ij} - t) = \sqrt{n\bar{N}b} \sigma_{K_1}^2 b^2 \Psi_{2n}$ . Since  $\tilde{K}_1$  i of o de (1, 3), Theo em 1 implie  $\Psi_{2n} = f'(t) + O_p(1/\sqrt{n\bar{N}b^3})$ , which ield  $\sqrt{n\bar{N}b} \sigma_{K_1}^2 b^2 \Psi_{2n} = \sqrt{n\bar{N}b^5} \sigma_{K_1}^2 f'(t) + \sigma_{K_1}^2 O_p(b) = o_p(1)$  b ob e ing  $n\bar{N}b^5 \rightarrow d^2$  fo  $0 \leq d < \infty$ . Since  $\hat{f}(t) \xrightarrow{p} f(t)$  and  $|\hat{\alpha}_1(t) - \mu'(t)| = O_p(1/\sqrt{n\bar{N}b^3}) = o_p(1)$ , we find

$$\begin{aligned} \lim_{n \rightarrow \infty} \sqrt{n\bar{N}b} [\hat{\mu}_L(t) - \mu(t)] &\stackrel{\mathcal{D}}{\Rightarrow} \lim_{n \rightarrow \infty} \sqrt{n\bar{N}b} \\ &\times \left\{ \frac{\sum_i \frac{1}{EN} \sum_j w_{ij} Y_{ij} - \mu'(t) \sum_i \frac{1}{EN} \sum_j w_{ij} T_{ij} + t \mu'(t) \sum_i \frac{1}{EN} \sum_j w_{ij}}{\sum_i \frac{1}{EN} \sum_j w_{ij}} - \mu(t) \right\}. \end{aligned}$$

U ing he ke nel  $K_1$  of o de (0, 2), e e-define  $\Psi_{\lambda n}$ ,  $1 \leq \lambda \leq 3$ , h o gh  $\psi_1(u, y) = y$ ,  $\psi_2(u, y) = u$  and  $\psi_3(u, y) \equiv 1$ , e ing  $v = 0$ ,  $k = 2$ ,  $l = 3$  and  $H(x_1, x_2, x_3) = [x_1 - \mu'(t)x_2 + t\mu'(t)x_3]/x_3$ . Then (13) follo b appl ing Theo em 1.  $\square$

### 3.2. Asymptotic distributions of covariance estimators

No e ha in model (1),  $cov(Y_{ij}, Y_{ik}|T_{ij}, T_{ik}) = cov(X(T_{ij}), X(T_{ik})) + \sigma^2 \delta_{jk}$ , he e  $\delta_{jk} \neq 1$  if  $j = k$  and 0 o he wi e. Le  $C_{ijk} = (Y_{ij} - \hat{\mu}(T_{ij}))(Y_{ik} - \hat{\mu}(T_{ik}))$  be he a co iance , he e  $\hat{\mu}(t)$  i he e ima ed mean f nç ion ob ained f om he p e io ep, fo in ance,  $\hat{\mu}(t) = \hat{\mu}_N(t)$  o  $\hat{\mu}(t) = \hat{\mu}_L(t)$ . I i ea o ee ha  $E[C_{ijk}|T_{ij}, T_{ik}] \approx cov(X(T_{ij}), X(T_{ik})) + \sigma^2 \delta_{jk}$ . The efo e,

The diagonal of the  $a_{jk}$  covariance matrix  $C_{ijk}$ ,  $j \neq k$ , would be included in the input data for the covariance function modeling, while the off-diagonal elements  $C_{ijk}$ ,  $i \neq j$ , would be included in § 3.2.1 and Lee [12] and Yao et al. [15].

Commonly used nonparametric models include the local linear model and the Nadaraya-Watson model, both defined as follows:

$$\begin{aligned}\widehat{C}_N(s, t) &= \left[ \sum_{i=1}^n \sum_{j \neq k} K_2 \left( \frac{s - T_{ij}}{h}, \frac{t - T_{ik}}{h} \right) C_{ijk} \right] / \\ &\quad \left[ \sum_{i=1}^n \sum_{j \neq k} K_2 \left( \frac{s - T_{ij}}{h}, \frac{t - T_{ik}}{h} \right) \right], \\ \widehat{C}_L(s, t) &= \hat{\beta}_0(s, t) = \min_{\beta} \left\{ \sum_{i=1}^n \sum_{j \neq k} K_2 \left( \frac{s - T_{ij}}{h}, \frac{t - T_{ik}}{h} \right) \right. \\ &\quad \times [C_{ijk} - f(\beta, (s, t), (T_{ij}, T_{ik}))] \left. \right\} \left\{ \sqrt{\sum_{i=1}^n \sum_{j \neq k} K_2 \left( \frac{s - T_{ij}}{h}, \frac{t - T_{ik}}{h} \right)} \right\}^{-1}.\end{aligned}\tag{16}$$

$\phi_1(t_1, t_2, y_1, y_2) = (y_1 - \mu(t_1))(y_2 - \mu(t_2))$ ,  $\phi_2(t_1, t_2, y_1, y_2) = y_1 - \mu(t_1)$ , and  $\phi_3(t_1, t_2, y_1, y_2) \equiv 1$ , then  $\mathbb{P}_{t,s \in \mathcal{T}} |\Phi_{pn}| = O_p(1)$ , for  $p = 1, 2, 3$ , by Lemma 1 of Yao et al. [16]. This implies  $\mathbb{P}_{t,s \in \mathcal{T}} |\Phi_{2n}| O_p(1/(\sqrt{n}b)) = O_p(1/(\sqrt{n}b))$  and  $\mathbb{P}_{t,s \in \mathcal{T}} |\Phi_{3n}| O_p(1/(\sqrt{n}b)) = O_p(1/(\sqrt{n}b))$ . Since  $\mathbb{P}_{t \in \mathcal{T}} |\hat{\mu}(t) - \mu(t)|^2 = O_p(1/(nb))$  is negligible compared to  $\Phi_{1n}$ , we have Nada and Wang on the image of  $\tilde{C}_N(s, t)$ , of  $C(s, t)$  obtained from  $C_{ijk}$  in a more practical way than obtained from  $\tilde{C}_{ijk}$ , denoted by  $\tilde{C}_N(t, s)$ .

The proof is given in the following section of the paper. To compare  $\gamma_N(s, t)$ , we have  $DH(m_1, m_2) = (1/m_2, -m_1/m_2^2)$ , and note  $m_1(s, t) = \int_{\mathcal{R}^2} (y_1 - \mu(s))(y_2 - \mu(t)) g_2(s, t, y_1, y_2) dy_1 dy_2 = f_2(s, t) C(s, t)$  and  $m_2(s, t) = f_2(s, t)$ . One has  $(d^2/dt^2)m_1(s, t) = [(d^2 f_2/dt^2)C + 2(df_2/dt)(dC/dt) + f_2(d^2C/dt^2)](s, t)$ ,  $(d^2/dt^2)m_2(s, t) = d^2 f_2(s, t)/dt^2$  and similarly obtain  $\omega_{11} = \|K_2\|^2 \int_{\mathcal{R}^2} (y_1 - \mu(s))^2 (y_2 - \mu(t))^2 g_2(s, t, y_1, y_2) dy_1 dy_2 = E[(Y_1 - \mu(T_1))^2(Y_2 - \mu(T_2))^2 | T_1 = s, T_2 = t] f_2(s, t) \|K_2\|^2$ ,  $\omega_{12} = \omega_{21} = \|K_2\|^2 f_2(s, t) C(s, t)$ ,  $\omega_{22} = \|K_2\|^2 f_2(s, t)$ , and  $DH(m_1, m_2) = (1/m_2, -m_1/m_2^2)$ , yielding the same result in (12).  $\square$

**Corollary 4.** If the assumptions (A1.1), (A1.2), and (C1.1)–(C3) hold with  $|\mathbf{v}| = 0$  and  $|\mathbf{k}| = 2$ , then

$$\begin{aligned} & \sqrt{n\bar{N}(\bar{N}-1)h^2}[\tilde{C}_L(s, t) - C(s, t)] \\ & \xrightarrow{\mathcal{D}} \mathcal{N}\left(\frac{e}{4}\sigma_{K_2}^2[d^2C(s, t)/ds^2 + d^2C(s, t)/dt^2], \frac{v(s, t)\|K_2\|^2}{f_2(s, t)}\right), \end{aligned} \quad (19)$$

where  $e$  is as in (C3),  $v(s, t) = \text{var}\{(Y_1 - \mu(T_1))(Y_2 - \mu(T_2)) | T_1 = s, T_2 = t\}$ ,  $\sigma_{K_2}^2 = \int_{\mathcal{R}^2} (u^2 + v^2) K_2(u, v) du dv$ ,  $\|K_2\|^2 = \int_{\mathcal{R}^2} K_2^2(u, v) du dv$ .

**Proof.** In analogy to the proof of Corollary 3, the local linear estimator  $\tilde{C}_L(s, t)$  obtained from  $C_{ijk}$  is a more practical way than obtained from  $\tilde{C}_{ijk}$ , denoted by  $\tilde{C}_L(t, s)$ . Also denote the estimation of (17), after comparing  $\tilde{C}_{ijk}$  to  $C_{ijk}$ , by  $\tilde{\beta}(s, t) = (\tilde{\beta}_0(s, t), \tilde{\beta}_1(s, t), \tilde{\beta}_2(s, t))$ , and in fact  $\tilde{\beta}_0(s, t) = \tilde{C}_L(s, t)$ . From the implications, let  $W_{ijk} = K_2((s - T_{ij})/h, (t - T_{ik})/h)/(nh^2)$  and  $\sum_{i,j \neq k} W_{ijk}$  is a abbreviation of  $\sum_{i=1}^n \sum_{j \neq k} W_{ijk}$ . Algebraic calculation yields that

$$\tilde{C}_L = \frac{\sum_{i,j \neq k} \tilde{C}_{ijk} W_{ijk} - \tilde{\beta}_1 \sum_{i,j \neq k} W_{ijk} T_{ij} + \tilde{\beta}_1 \sum_{i,j \neq k} W_{ijk} s - \tilde{\beta}_2 \sum_{i,j \neq k} W_{ijk} T_{ik} + \tilde{\beta}_2 \sum_{i,j \neq k} W_{ijk} t}{\sum_{i,j \neq k} W_{ijk}},$$

$$\tilde{\beta}_1 = \frac{R_{00}(S_{10}S_{02} - S_{01}S_{11}) + R_{10}(S_{00}S_{02} - S_{01}S_{20}) - R_{01}(S_{00}S_{11} - S_{10}S_{02})}{S_{00}S_{20}S_{02} - S_{00}S_{11}^2 - S_{10}^2S_{02} + S_{10}S_{01}S_{11} + S_{20}S_{10}S_{11} - S_{01}S_{20}^2},$$

$$\tilde{\beta}_2 = \frac{R_{00}(S_{10}S_{11} - S_{01}S_{02}) - R_{10}(S_{00}S_{11} - S_{01}S_{20}) + R_{01}(S_{00}S_{20} - S_{10}^2)}{S_{00}S_{20}S_{02} - S_{00}S_{11}^2 - S_{10}^2S_{02} + S_{10}S_{01}S_{11} + S_{20}S_{10}S_{11} - S_{01}S_{20}^2},$$

the estimate

$$R_{pq} = \sum_{i,j \neq k} W_{ijk} (T_{ij} - s)^p (T_{ik} - t)^q \tilde{C}_{ijk}, \quad S_{pq} = \sum_{i,j \neq k} W_{ijk} (T_{ij} - s)^p (T_{ik} - t)^q.$$

No e ha  $\tilde{\beta}_1$  and  $\tilde{\beta}_2$  a e local linea e ima o of he pa al de i a i e of  $C(s, t)$ ,  $dC(s, t)/ds$  and  $dC(s, t)/dt$ , e pec i el . In analog o he p oof of Co olla 2, i can be ho wn ha  $|\tilde{\beta}_1(s, t) - dC(s, t)/ds| = O_p(1/\sqrt{nEN(N-1)h^4})$  and  $|\tilde{\beta}_2(s, t) - dC(s, t)/dt| = O_p(1/\sqrt{nN(\bar{N}-1)h^4})$  b appl ing Theo em 2. Then one can , b i , e dc(s, t)/ds,  $dC(s, t)/dt$  fo  $\tilde{\beta}_1(s, t)$ ,  $\tilde{\beta}_2(s, t)$  in  $\tilde{C}_L(s, t)$ , and deno e he e , l ing e ima o b  $C_L^*(s, t)$ . I i ea , o ee ha

$$\lim_{n \rightarrow \infty} \sqrt{n\bar{N}(\bar{N}-1)h^2} [C_L(s, t) - C(s, t)] \stackrel{\mathcal{D}}{\Rightarrow} \lim_{n \rightarrow \infty} \sqrt{n\bar{N}(\bar{N}-1)h^2} [C_L^*(s, t) - C(s, t)].$$

We define  $\Phi_{\lambda n}$ ,  $1 \leq \lambda \leq 4$ , h o g h  $\phi_1(s, t, y_1, y_2) = (y_1 - \mu(s))(y_2 - \mu(t))$ ,  $\phi_2(s, t, y_1, y_2) = T_m(s)T_j(t)$

he in Coolla ie 3 and 4,  $\hat{f}(t)$  replaced by  $1/|\mathcal{T}|$  and  $f(s, t)$  replaced by  $1/|\mathcal{T}|^2$ , where  $|\mathcal{T}|$  is the length of the interval.

## 5. Simulation study

A numerical study is conducted to evaluate the performance of the proposed local polynomial mean estimator. The key finding is that the proposed estimator is more efficient than the kernel estimator in terms of mean squared error, especially when the sample size is small and the bandwidth is large. The influence of the local polynomial mean estimator on the estimation of the mean function is significant, particularly in the presence of nonparametric regression functions.

We first generate  $M = 200$  ample samples consisting of  $n = 50$  i.i.d. random vectors from each. Following model (1), the individual process has a mean function  $\mu(t) = (t - 1/2)^2$ ,  $0 \leq t \leq 1$ , which has a constant second derivative  $\mu''(t) = 2$ , and a constant variance  $\sigma^2 = 0.02$ . A random sample of size  $n$  is obtained by each  $N_i$  chosen from  $\{2, 3, 4, 5\}$ . The likelihood function of the observations follows a multinomial distribution on  $[0, 1]$ , i.e.,  $T_{ij} \sim U[0, 1]$ . For comparison, we generate  $M = 200$  ample samples of  $n = 50$  i.i.d. random vectors from which have the same form as in model (1) but no higher-order terms. The resulting  $\xi_{i1} = 0$  and  $\varepsilon_{ij} \sim N(0, \sqrt{\lambda_1 + \sigma^2})$  lead to independent data with the same mean and variance function. The effect of the number of data points on the local polynomial mean estimator is studied and independent ample samples are generated for  $n = 200$ , each from a uniform distribution on  $[0, 1]$ .

The estimated mean function  $\hat{f}(t)$  is calculated using Epanechnikov kernel function, i.e.,  $K_1(u) = 3/4(1 - u^2)\mathbf{1}_{[-1,1]}(u)$ , where  $\mathbf{1}_A(u) = 1$  if  $u \in A$  and 0 otherwise. Note that  $n(\bar{N})b^{2k+1} \rightarrow d^2$  in (B3),  $\mu''(t) = 2$ ,  $\text{var}(Y|T = t) = \lambda_1 + \sigma^2 = 0.02$ , and the design density  $f(t) = 1$ , where  $k = 2$  for local polynomial mean estimator and  $b$  is the bandwidth. The mean function is the local polynomial mean estimator  $\hat{\mu}_L(t)$ , which is applicable for both cases and independent data. Since the bias and variance of the local polynomial mean estimator  $\hat{\mu}_L(t)$  are  $\text{E}[\hat{\mu}_L(t)] - \mu(t)$  and  $\text{var}(\hat{\mu}_L(t))$ , respectively, one can calculate the local polynomial mean estimator  $\hat{\mu}_L(t)$  by using the formula  $\hat{\mu}_L(t) = \sum_{i=1}^n N_i \hat{f}(t)$ . The local polynomial mean estimator  $\hat{\mu}_L(t)$  is then compared with the empirical mean estimator  $\bar{Y}$  and the kernel mean estimator  $\hat{f}(t)$ .

$$\text{AIBIAS} = \frac{1}{2}\sigma_{K_1}^2 b^4, \quad \text{AIVAR} = \frac{0.02 \times \|K_1\|^2}{n\bar{N}b}, \quad (20)$$

and the absolute mean square error  $\text{AIMSE} = \text{AIBIAS} + \text{AIVAR}$ , where  $\sigma_{K_1}^2 = \int u^2 K_1(u) du$ ,  $\|K_1\|^2 = \int K_1^2(u) du$  and  $\bar{N} = (1/n) \sum_{i=1}^n N_i$ , while the empirical mean estimator is denoted by  $\text{EIBIAS}$ ,  $\text{EIVAR}$  and  $\text{EIMSE}$ .

The absolute mean square error of the local polynomial mean estimator is plotted in Fig. 1 for the case of independent data with sample size  $n = 50$ . The results show that the local polynomial mean estimator is more efficient than the kernel mean estimator in terms of mean squared error, particularly when the bandwidth is large. The influence of the local polynomial mean estimator on the estimation of the mean function is significant, particularly in the presence of nonparametric regression functions.

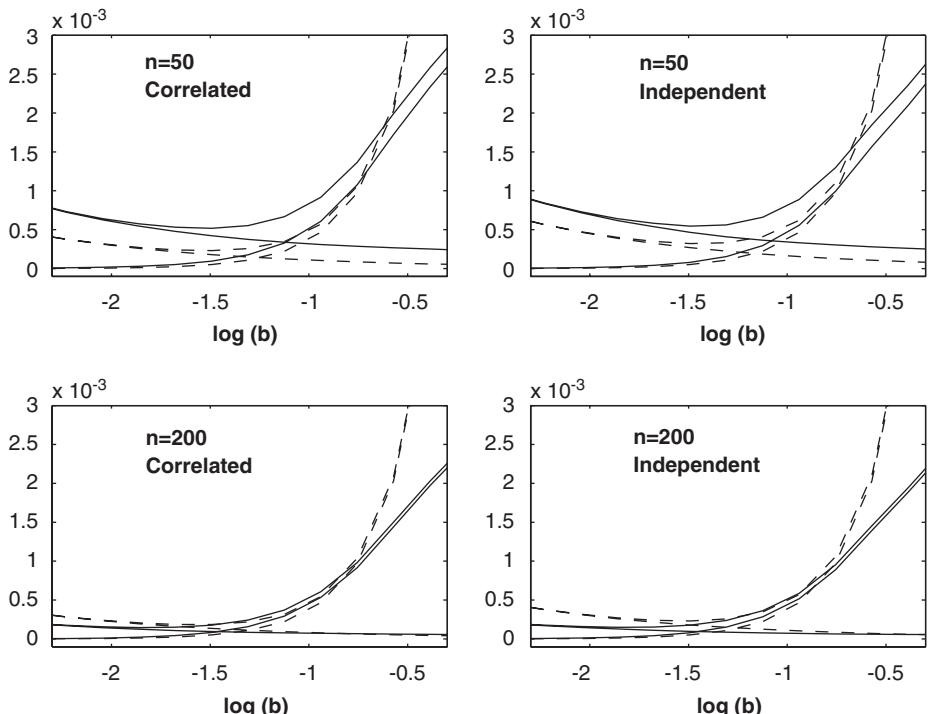


Fig. 1. Shown are the empirical quantiles (solid, dashed and dotted lines) for EIBIAS, EIVAR, and EIMSE under correlated (left panel) and independent (right panel) data with different sample size  $n = 50$  (top panel) and  $n = 200$  (bottom panel), where each band includes the mean quantile and its standard deviation. In each panel, the legend indicates the estimator: solid line for EIBIAS, dashed line for EIVAR, and dotted line for EIMSE. The x-axis is  $\log(b)$  and the y-axis is scaled by  $10^{-3}$ .

empirical quantiles for EIBIAS, EIVAR and EIMSE for both correlated and independent data. For the imbalanced data with the same sample size  $n$ , the empirical quantiles for correlated and independent data are well comparable in pattern and magnitude. This provides evidence that the influence of the local polynomial estimation compared to the ordinary least squares method is indeed negligible. The influence on the empirical behavior of the local polynomial estimation compared to the ordinary least squares method is mainly due to the fact that it is independent of the error term, which is consistent with the theoretical result.

## 6. Discussion

In this paper, the empirical distribution function of kernel-based nonparametric quantiles is investigated

de ign de c ibed in (A1.1) and (A1.2), fi ed eq all paced de ign de c ibed in (A1\*), and ome ca e l ing be seen hem. The p opo ed e , l co ld al o be e ended o mo e complica ed ca e , ch a panel da a \*he ob e a ion fo diffe en , bjec a e ob ained a a e ie of common im e poin d ing a longi , dinal follo w p. If con ide ing andom de ign, he den i of he j h ob e a ion, im e  $T_j$  co ld be a , med o be  $f_j(t)$ , hen he e , l a e adil applied o hi ca e wi h app op ia e modifica ion wi h e pec o he diffe en ma ginal den i ie .

The gene al a mp o ic di , ib ion e , l in , ni a ia e and bi a ia e moo hing e ing a e applied o he ke nel-ba ed e ima o of he mean and co a iance f n c ion , which ield a mp o ic no mal di , ib ion of he e e ima o . To he be , of o kno wledge, he e a eno a mp o ic di , ib ion e , l a ailable in li e a , e fo nonpa ame ic e , ima o of co a iance f n c ion ob ained f om ob e ed noi longi , dinal o f n c ional da a . Thi p o ide heo e ical ba i and p ac ical g idance fo he nonpa ame ic anal i of f n c ional o longi , dinal da a wi h impo - an po en ial applica ion , ha a e ba ed on he a mp o ic di , ib ion . Fo e ample, a mp o ic confidence band o egion fo he eg e ion c e o he co a iance , face can be con c ed ba ed on hei a mp o ic di , ib ion . Since, d e o hei hea comp a ional load, commonl ed p oced e (, ch a c o - alida ion) fo band wi h elec ion in wi o-dimen ional e ing a e no fea ible, one impo an e ea ch p oblem i , o eek efficien app oache fo choo ing , ch moo hing pa ame e . Al o f n c ional p incipal componen anal i , an inc ea ingl pop la ool fo f n c ional da a anal i , i ba ed on eigen-decompo ion of he e ima ed co a iance f n c ion. Th , he infl ence of he a mp o ic p ope ie of co a iance e ima o on he e ima ed eigenf nc ion i ano he po en ial e ea ch of in e e .

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