

# Factor Profiling for Ultra High Dimensional Variable Selection

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# Basic Background

- Practical Motivation
  - Microarray
  - Supermarket
  - Search Engine
- Existing Methods
  - AIC and BIC
  - LASSO and SCAD
  - SIS and FR

# Screening Methods

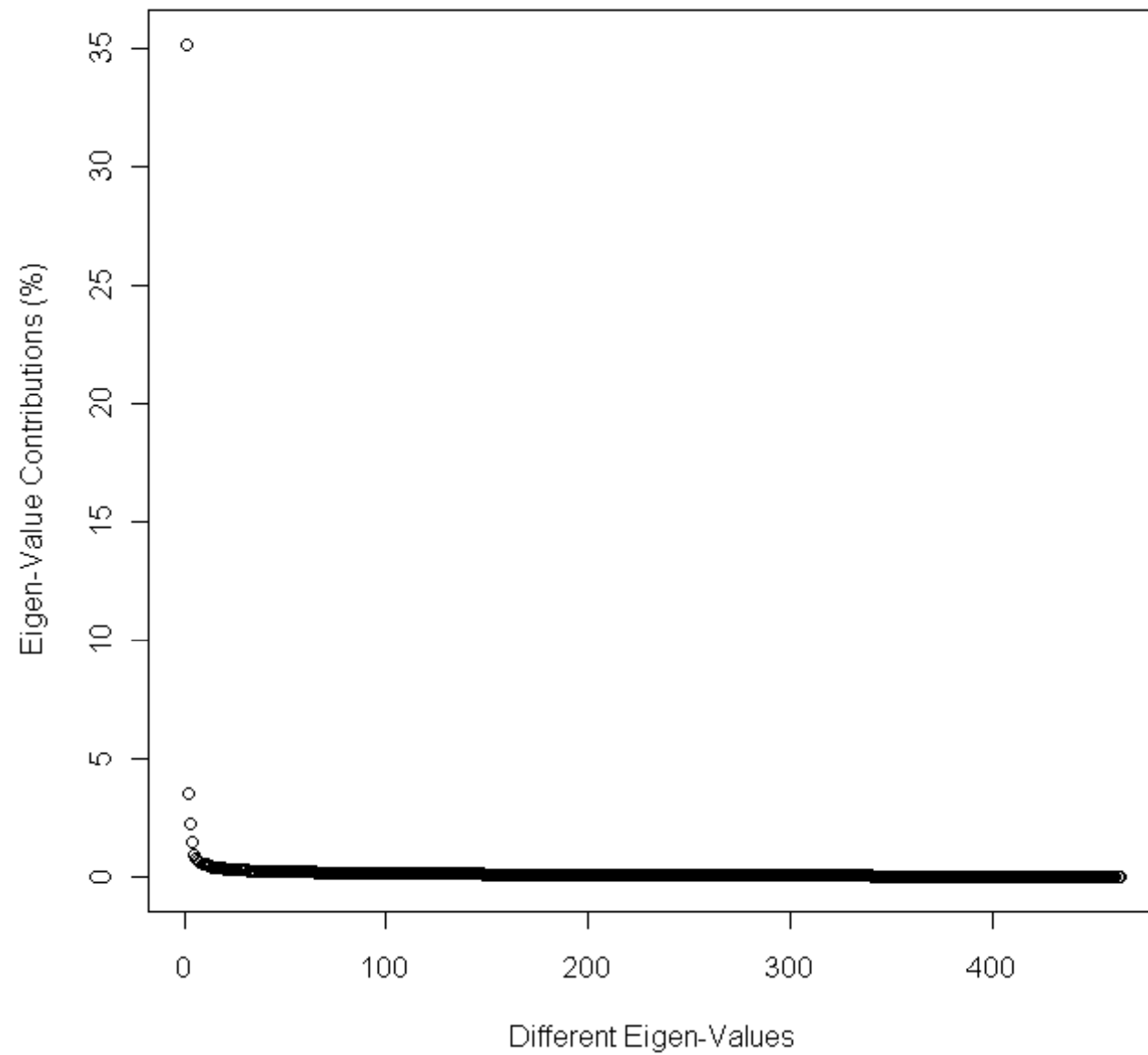
- SIS (Fan and Lv, 2008, JRSSB)
- FR (Wang, 2009, JASA)
- We typically wish  $\text{cov}(X)$  to be well behaved and better not to be highly singular.
- What is the real world?

# A Supermarket Example

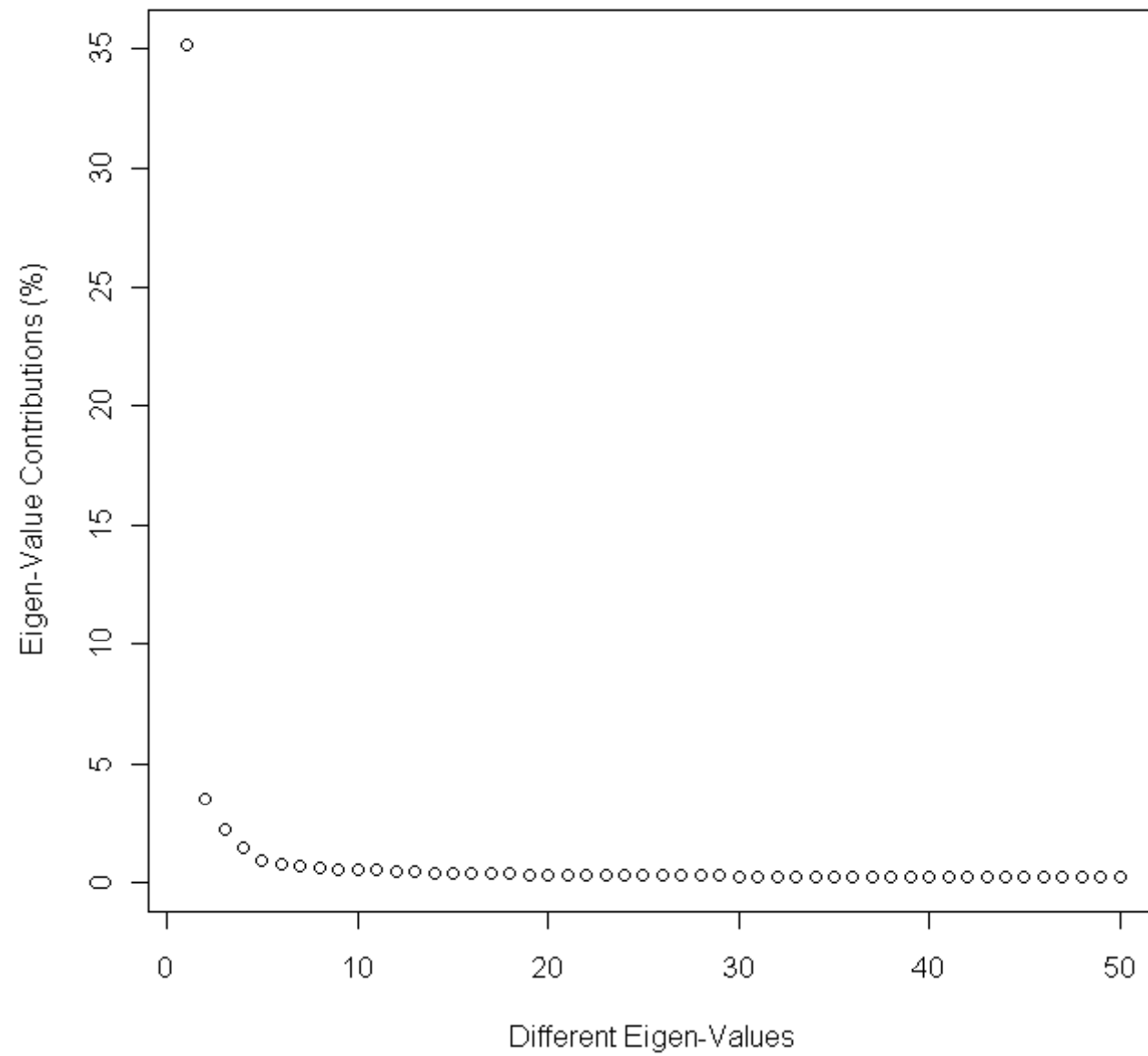
- Data Resource:
  - A major domestic super market in Northern China.
- Response:
  - Daily customer volume for a total of 464 days.
- Predictor:
  - Daily sales volume for a total of 6398 products.
- Objective:
  - Predict next day's customer volume.



**All Eigen-Values**



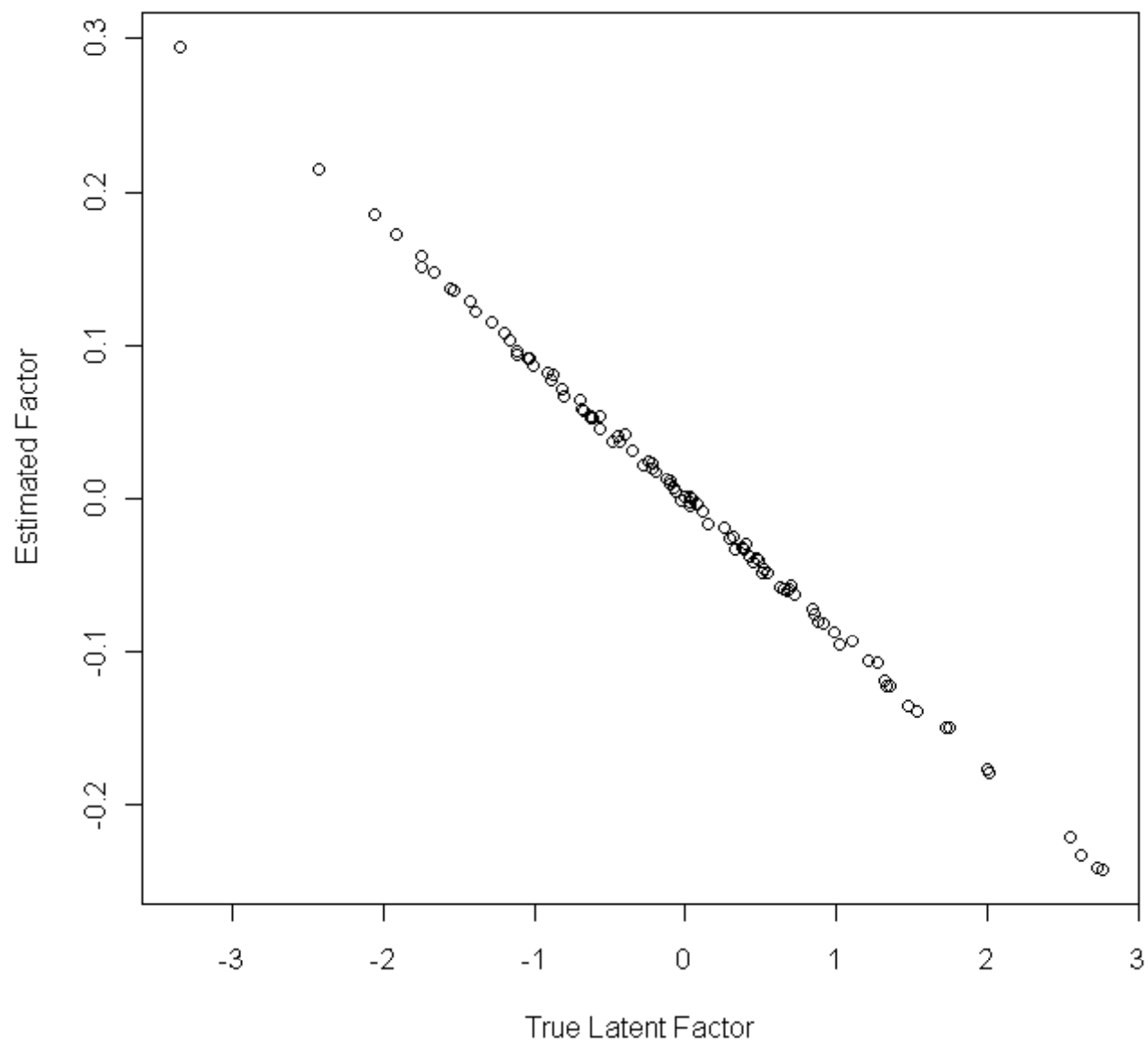
**Top 50 Eigen-Values**



# A Simple Experiment

- Randomly generate a high dimensional data according to a very simple factor model
  - Sample Size = 100;
  - Predictor Dimension = 1000;
  - Factor Model:  $X = \text{Latent Factor} + \text{Error}$
  - Estimation: Standard SVD
  - Question: Can we capture latent factor consistently or not?

**Estimating Latent Factor by SVD**





# A Theoretical Framework

- To model the regression relationship between  $Y_i$  and  $X_i$ , we assume that

$$Y_i = X_i^\top \theta + \varepsilon_i, \quad (2.1)$$

where  $\varepsilon_i$  is a random noise with mean 0 and variance  $\sigma_\varepsilon^2$ ;  $\theta = (\theta_1, \dots, \theta_p)^\top \in \mathbb{R}^p$  is a  $p$ -dimensional coefficient vector and its true value is given by  $\theta_0 = (\theta_{01}, \dots, \theta_{0p})^\top \in \mathbb{R}^p$ .

- To model the factor structure, we follow Fan et al. (2008) and assume

$$X_i = BZ_i + \tilde{X}_i, \quad (2.2)$$

where  $Z_i = (Z_{i1}, \dots, Z_{id})^\top \in \mathbb{R}^d$  is a  $d$ -dimensional latent factor,  $B = (b_{jk}) \in \mathbb{R}^{p \times d}$  is the loading matrix, and  $\tilde{X}_i = (\tilde{X}_{i1}, \dots, \tilde{X}_{ip})^\top \in \mathbb{R}^p$  represents the information contained in  $X_i$  but missed by  $Z_i$ .

# Endogeneity Issue

In the endogeneity problem, we allow that  $\varepsilon_i$  to be correlated with  $X_i$  through the common factor  $Z_i$  as

$$\varepsilon_i = Z_i^\top \alpha + \tilde{\varepsilon}_i, \quad (2.3)$$

where  $\alpha = (\alpha_1, \dots, \alpha_d)^\top \in \mathbb{R}^d$  is a  $d$ -dimensional vector and its true value is given by  $\alpha_0 \in \mathbb{R}^d$ . Moreover,  $\tilde{\varepsilon}_i$  is some random noise independent of both  $Z_i$  and  $\tilde{X}_i$ . We then should have  $\text{var}(\tilde{\varepsilon}_i) = \tilde{\sigma}_\varepsilon^2 \leq \text{var}(Y_i) = 1$ .

# Factor Profiling

- Profiled Response:  $\tilde{Y}_i = Y_i - Z_i^\top \gamma_0$  with  $\gamma_0 = B^\top \theta_0 + \alpha_0$ .
- Profiled Predictor and Noise:  $\tilde{X}_i$  and  $\tilde{\varepsilon}_i$ .
- Profiled Regression Model:  $\tilde{Y}_i = \tilde{X}_i^\top \theta_0 + \tilde{\varepsilon}_i$ .

# Estimating Factor Dimension

- Let  $(\hat{\lambda}_j, \hat{V}_j)$  be the  $j$ th ( $1 \leq j \leq n$ ) leading eigenvalue-eigenvector pair for the matrix  $\mathbb{X}\mathbb{X}^\top/(np) \in \mathbb{R}^{n \times n}$ . Thus, we should have  $\hat{\lambda}_1 \geq \hat{\lambda}_2 \geq \dots \geq \hat{\lambda}_n$ .



- Thus, if we define an eigenvalue ratio criterion as  $\hat{\lambda}_j/\hat{\lambda}_{j+1}$  with  $\hat{\lambda}_0 = 1$  and  $1 \leq j \leq (n-1)$ , we should expect its maximum value to happen at  $j = d_0$ .
- Consequently, the true structure dimension can be estimated by

$$\hat{d} = \operatorname{argmax}_{0 \leq j \leq d_{\max}} (\hat{\lambda}_j/\hat{\lambda}_{j+1}),$$

where  $d_{\max}$  is a pre-specified maximum factor dimension.

# Theoretical Properties

**Theorem 1.** *Assume technical conditions (A1)–(A2) as given in the Appendix. Assume that the true parameter  $d_0$  is in the interior of the parameter space  $\mathcal{D}$ . Then, if the sample size  $n$  is large enough, we should have  $P(\hat{d} = d_0) \rightarrow 1$  as  $n \rightarrow \infty$ .*

# Estimating Factor Subspace

By  $\mathbf{Y}^{T+1}$  with a correctly specified factor dimension (i.e.,  $d = d_0$ ), we can subsequently construct a least squares type objective function as

$$\mathcal{O}(\mathbb{Z}, B) = (np)^{-1} \sum_{j=1}^p \|\mathbb{X}_j - \mathbb{Z}\beta_j\|^2$$

with  $\beta_j = (b_{j1}, \dots, b_{jd})^\top \in \mathbb{R}^d$ . We know immediately that  $B = (\beta_1, \dots, \beta_p)^\top \in \mathbb{R}^{p \times d}$ . Then,  $\mathcal{S}(\mathbb{Z})$  can be estimated by minimizing  $\mathcal{O}(\mathbb{Z}, B)$  with respect to both  $\mathbb{Z} \in \mathbb{R}^{n \times d}$  and  $B \in \mathbb{R}^{p \times d}$ .

# Estimation Accuracy

To quantify the estimation accuracy of  $\mathcal{S}(\widehat{\mathbb{Z}})$ , the following two discrepancy measures are considered. They are, respectively,

$$D_1(\mathbb{Z}, \widehat{\mathbb{Z}}) = n^{-1} \text{tr} \left\{ \mathbb{Z}^\top Q(\widehat{\mathbb{Z}}) \mathbb{Z} \right\} \text{ and } D_2(\mathbb{Z}, \widehat{\mathbb{Z}}) = \text{tr} \left\{ H(\mathbb{Z}) - H(\widehat{\mathbb{Z}}) \right\}^2.$$

**Theorem 2.** *Assume  $d = d_0$  and the technical conditions (A1)–(A3) as given in the Appendix A, then we should have both  $D_1(\mathbb{Z}, \widehat{\mathbb{Z}}) = O_p(n^{-1})$  and  $D_2(\mathbb{Z}, \widehat{\mathbb{Z}}) = O_p(n^{-1})$ .*

# Profiled Independent Screening

With interest  $\theta_0 \in \mathbb{R}^p$ , we can generate profile data  $\hat{\mathbf{Y}} \in \mathbb{R}^n$  and  $\hat{\mathbf{X}} := Q(\hat{\mathbf{Z}})\hat{\mathbf{X}}'$  with  $\hat{\mathbf{X}}' := (\hat{\mathbf{X}}_1', \dots, \hat{\mathbf{X}}_p')' \in \mathbb{R}^{n \times p}$ .

- Subsequently, the simple method of SIS can be applied to  $\hat{\mathbf{Y}}$  and  $\hat{\mathbf{X}}$  directly, and the resulting estimate is path consistent (Leng et al., 2006). We refer to such a method as PIS.
- More specifically, PIS estimates  $\theta_j$  by  $\hat{\theta}_j = (n^{-1}\hat{\mathbf{X}}_j^\top \hat{\mathbf{X}}_j)^{-1}(n^{-1}\hat{\mathbf{Y}}^\top \hat{\mathbf{X}}_j)$ .

**Theorem 3.** Assume  $d = d_0$  and the technical conditions (A1)–(A3) as given in the

Agg. as above. As  $n \rightarrow \infty$ , we have  $\|\hat{\theta}_j - \theta_j\| \leq O_p(\sqrt{\frac{\log p}{n}})$ .



# A BIC Criterion

Previous subsection proves that PIS is path consistent, which implies that  $P(\mathcal{M}_T = \mathcal{M}_{(|\mathcal{M}_T|)}) \rightarrow 1$  as  $n \rightarrow \infty$ . However, for a real application, the value of  $|\mathcal{M}_T|$  is unknown. Thus, even if the solution path is given, one still needs a statistically sound criterion to decide which model in  $\mathbb{M}$  is mostly plausible. To this end, we proposed here the following heuristic BIC-type selection criterion,

$$\text{BIC}(\mathcal{M}) = \log \text{RSS}(\mathcal{M}) + |\mathcal{M}| \cdot \log n \cdot (\log p/n), \quad (3.1)$$

where  $\text{RSS}(\mathcal{M}) = \|\hat{\mathbf{Y}} - \sum_{j \in \mathcal{M}} \hat{\theta}_j \hat{\mathbf{X}}_j\|^2$  is the residual sum of squares. Then the best model can be selected as  $\hat{\mathcal{M}} = \text{argmin}_{\mathcal{M} \in \mathbb{M}} \text{BIC}(\mathcal{M})$ .

# Profiled Sequential Screening

Step (1) (*Initialization*). Set  $\mathcal{M}_{(0)}^* = \emptyset$  and  $\hat{\mathbf{Y}}^{(0)} = \hat{\mathbf{Y}}$ , i.e., the factor profiled response.

Step (2) (*Sequential Screening*).

(2.1) (*Estimation*). In the  $k$ th step ( $k \geq 1$ ), we are given  $\mathcal{M}_{(k-1)}^*$  and also

$\hat{\mathbf{Y}}^{(k-1)}$ . Then, for every  $j \in \mathcal{M}_F \setminus \mathcal{M}_{(k-1)}^*$ , estimate its regression coefficient as  $\hat{\theta}_j^{(k)} = \{\hat{\mathbf{Y}}^{(k-1)\top} \hat{\mathbf{X}}_j\} / \|\hat{\mathbf{X}}_j\|^2$  and its correlation coefficient with the response as  $\hat{\zeta}_j^{(k)} = \{\hat{\mathbf{Y}}^{(k-1)\top} \hat{\mathbf{X}}_j\} / \{\|\hat{\mathbf{Y}}^{(k-1)}\| \cdot \|\hat{\mathbf{X}}_j\|\}$ .

By (2.2) (*Screening*), we then find  $a_k = \arg \min_{j \in \mathcal{M}_F \setminus \mathcal{M}_{(k-1)}^*} |\hat{\zeta}_j^{(k)}|$ , and update

$\mathcal{M}_{(k-1)}^* \cup \{a_k\}$  accordingly.  $\mathcal{M}_{(k)}^* =$

(2.3) (*Elimination*). According to  $a_k$ , we then get an updated response vector

$$\hat{\mathbf{Y}}^{(k)} = \hat{\mathbf{Y}} - \frac{\hat{\mathbf{Y}} \hat{\mathbf{X}}_{a_k}^\top \hat{\mathbf{X}}_{a_k} \hat{\mathbf{Y}}}{\hat{\mathbf{X}}_{a_k}^\top \hat{\mathbf{X}}_{a_k}} \quad \text{as } \hat{\mathbf{Y}}^{(k)} = \hat{\mathbf{Y}} - \frac{\hat{\mathbf{Y}} \hat{\mathbf{X}}_{a_k}^\top \hat{\mathbf{X}}_{a_k} \hat{\mathbf{Y}}}{\hat{\mathbf{X}}_{a_k}^\top \hat{\mathbf{X}}_{a_k}}.$$

g Step (2) for a total of  $n$  times, which leads a total Step (3) (*Solution Path*). Iteratin

# A Simulation Study

*Example 1.* This is an example borrowed from Fan and Lv (2008). Specifically, we fix  $d_0 = 1$ ,  $p = 5000$ , and  $n = 150$ .  $Z_i$  is generated from  $N(0, 1)$ .  $X_i$  is then simulated as (2.2), where  $b_{jk} = 1$  and  $\tilde{X}_i$  follows a  $p$ -dimensional standard normal distribution. Following Fan and Lv (2008), we assume the first  $|\mathcal{M}_T| = 3$  predictors to be relevant and their coefficients are given by  $\theta_{0j} = 5$  for  $1 \leq j \leq |\mathcal{M}_T|$ . Accordingly,  $\theta_{0j} = 0$  for every  $j > |\mathcal{M}_T|$ . Subsequently,  $Y_i$  is given by (2.1), where  $\varepsilon_i$  follows (2.3) with  $\alpha_0 = 0.8\sigma_\varepsilon$  and  $\tilde{\sigma}_\varepsilon = 0.6\sigma_\varepsilon$ . Lastly,  $\sigma_\varepsilon^2$  is particularly selected so that the signal-to-noise ratio, i.e.,  $\text{SNR} = \text{var}(X_i^\top \theta_0) / \sigma_\varepsilon^2$ , is given by 1, 2, or 5.

Signal Noise Ratio	Variable Selection Method	% of Correct Zeros	% of Incorrect Zeros	% of Correct fit	Average Model Size	Absolute Estimation Error
EXAMPLE 1						
1	SIS	100.0	77.2	0.0	1.0	25.4
	PIS	100.0	95.8	0.5	0.1	14.6
	PSS	100.0	95.8	0.5	0.1	14.6
2	SIS	100.0	70.3	0.0	1.0	21.3
	PIS	100.0	46.3	40.0	1.6	7.9
	PSS	100.0	43.3	45.5	1.7	7.4
5	SIS	100.0	67.0	0.0	1.0	18.4
	PIS	100.0	0.2	99.5	3.0	1.0
	PSS	100.0	0.0	100.0	3.0	0.9

# Real Example: Factor Dimension

As our first step, we need to estimate the dimension of the latent factor. We find that the first eigenvalue of the matrix  $\mathbb{X}\mathbb{X}^\top/(np)$  is as large as  $\hat{\lambda}_1 = 35.4\%$  while the second one is as small as  $\hat{\lambda}_2 = 3.5\%$ . The big difference as demonstrated between  $\hat{\lambda}_1$  and  $\hat{\lambda}_2$  suggests that the true factor dimension might be  $d_0 = 1$ . Such a conjecture is formally confirmed by MERC. We then fix  $d = 1$  throughout the rest of this example. Thereafter, the factor subspace  $\mathcal{S}(\hat{\mathbb{Z}})$  can be estimated and the profiled data  $(\hat{\mathbb{Y}}, \hat{\mathbb{X}})$  can be produced.

# Out of Sample Testing

For a real problem like this, the value of  $\theta_0$  is unknown. We thus have to rely on out-of-sample testing to compare different methods' estimation and/or prediction accuracy. We then conducted a total of 200 random experiments. For each experiment, we randomly split the entire dataset  $\mathcal{D} = \{1, \dots, 464\}$  into two parts. That is  $\mathcal{D} = \mathcal{D}_0 \cup \mathcal{D}_1$  with  $|\mathcal{D}_0| = n_0 = 400$  as the training data and  $|\mathcal{D}_1| = n_1 = 64$  as the testing data. Accordingly, we write  $\mathbb{X}_0 = \{X_i : i \in \mathcal{D}_0\} \in \mathbb{R}^{n_0 \times p}$ ,  $\mathbb{Y}_0 = \{Y_i : i \in \mathcal{D}_0\} \in \mathbb{R}^{n_0}$ ,  $\mathbb{X}_1 = \{X_i : i \in \mathcal{D}_1\} \in \mathbb{R}^{n_1 \times p}$ , and  $\mathbb{Y}_1 = \{Y_i : i \in \mathcal{D}_1\} \in \mathbb{R}^{n_1}$ . Notations for  $(\hat{\mathbb{X}}_0, \hat{\mathbb{X}}_1)$ ,  $(\hat{\mathbb{Y}}_0, \hat{\mathbb{Y}}_1)$ , and  $(\hat{\mathbb{Z}}_0, \hat{\mathbb{Z}}_1)$  are defined accordingly.

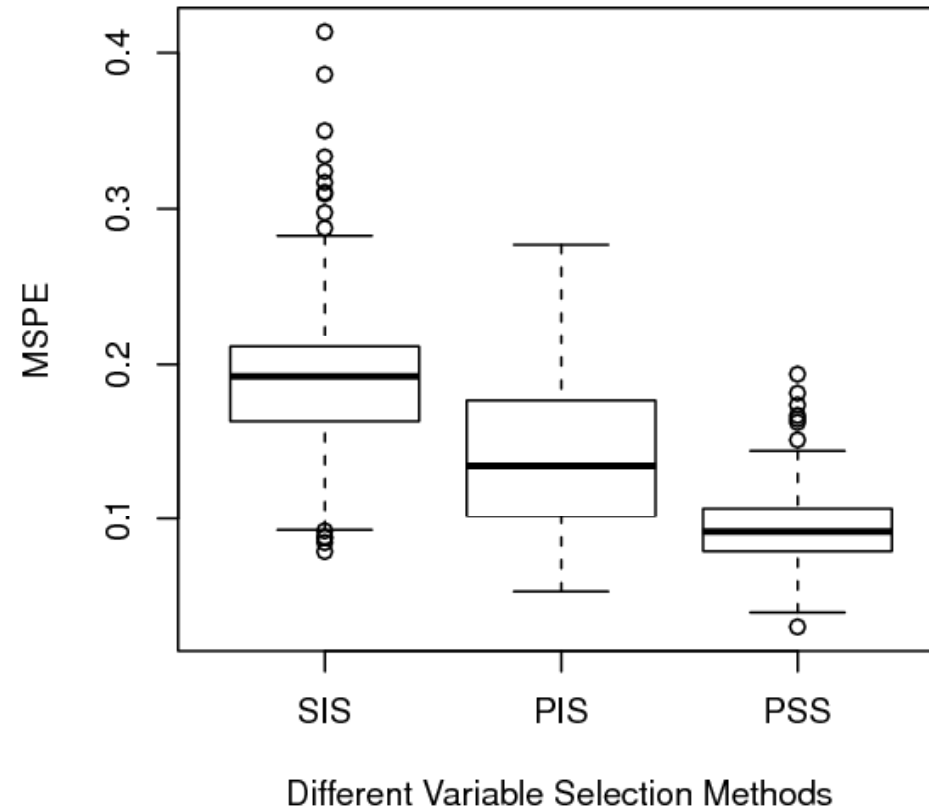


Figure 1: The real supermarket example. Boxplots for the median squared prediction errors (MSPE) based on 200 random replications.

Comments are very welcome!  
Many thanks!